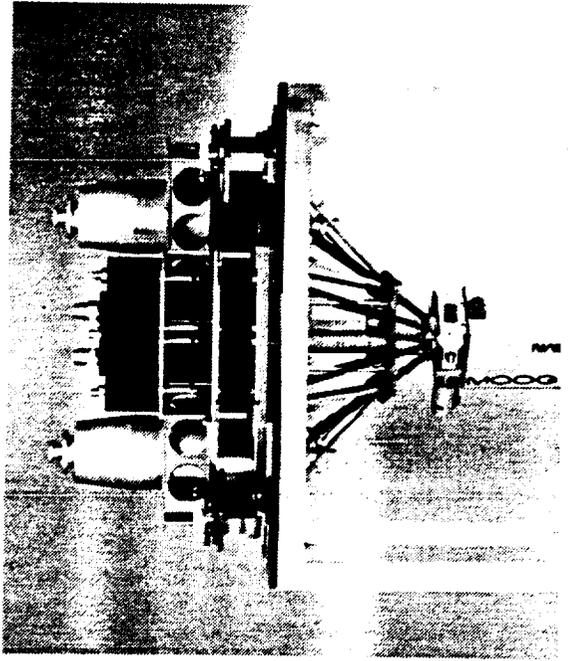
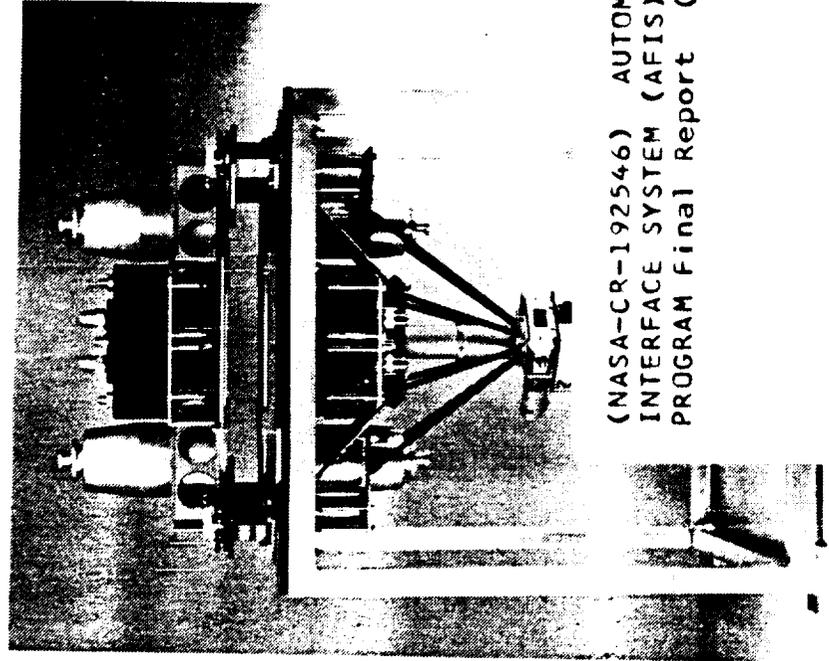


NAS8-37459

# AUTOMATED FLUID INTERFACE SYSTEM (AFIS) DEVELOPMENT PROGRAM

## FINAL REPORT



(NASA-CR-192546) AUTOMATED FLUID  
INTERFACE SYSTEM (AFIS) DEVELOPMENT  
PROGRAM Final Report (Moog) 81 p

N93-72797

Unclas

29/34 0166336

SEPTEMBER 12, 1990

**MOOG**  
SPACE PRODUCTS DIVISION

AUTOMATED FLUID INTERFACE SYSTEM

**NASA**  
MARSHALL SPACE FLIGHT CENTER

## **AFIS PROGRAM OVERVIEW**

**CUSTOMER:**

**ADVANCED PROGRAMS OFFICE  
NASA, MARSHALL SPACE FLIGHT CENTER  
HUNTSVILLE, ALABAMA**

**CONTRACT TYPE:**

**FIXED PRICE RESEARCH AND DEVELOPMENT CONTRACT**

**SCHEDULE:**

**FIFTEEN MONTHS (CLOSE-OUT BY 30 SEPT 90)**

**DELIVERABLES:**

**ONE FULL SCALE AFIS PROTOTYPE  
ONE TANKER/SPACECRAFT SIMULATOR  
REPORTS OF WORK**

## PROGRAM OBJECTIVE

### OVERALL OBJECTIVE:

- DEVELOP AND DEMONSTRATE AN AUTOMATED FLUID TRANSFER INTERFACE SYSTEM FOR USE WITH FUTURE TANKERS AND SPACECRAFT.

### GOALS:

- COMPLIANCE WITH ALL DESIGN REQUIREMENTS
- COMPATIBILITY WITH OMV AND OSCRS AS POTENTIAL TANKERS
- COMMON AFIS COMPATIBLE WITH BOTH RGDM AND TPDM
- REUSABLE FOR GROUND LAUNCHED SERVICING TO ALL ORBITS
- MINIMIZE LIFE CYCLE COSTS
- MAXIMIZE RELIABILITY
- RECONFIGURABLE FOR MONOPROP, BIPROP AND CRYOGENIC RESUPPLY

---

AUTOMATED FLUID INTERFACE SYSTEM

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## AFIS PROGRAM TEAM

**PROGRAM MANAGER/PROJECT ENGINEER:**    **JOE CARDIN**  
**(716) 687-4417**

**CONTRACT ADMINISTRATOR:**                **BILL MORRISH**

**DESIGN ENGINEERING SUPPORT:**  
**MECHANICAL DESIGN ENGINEER:**        **RICH MEINHOLD**  
**ELECTRICAL DESIGN ENGINEER:**        **JERRY NEUHAUSER**

**DEVELOPMENT LAB SUPPORT:**  
**MECHANICAL A&T TECHNICIAN:**        **DAN ERTL**  
    **ED MADAR**

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**AUTOMATED FLUID INTERFACE SYSTEM**

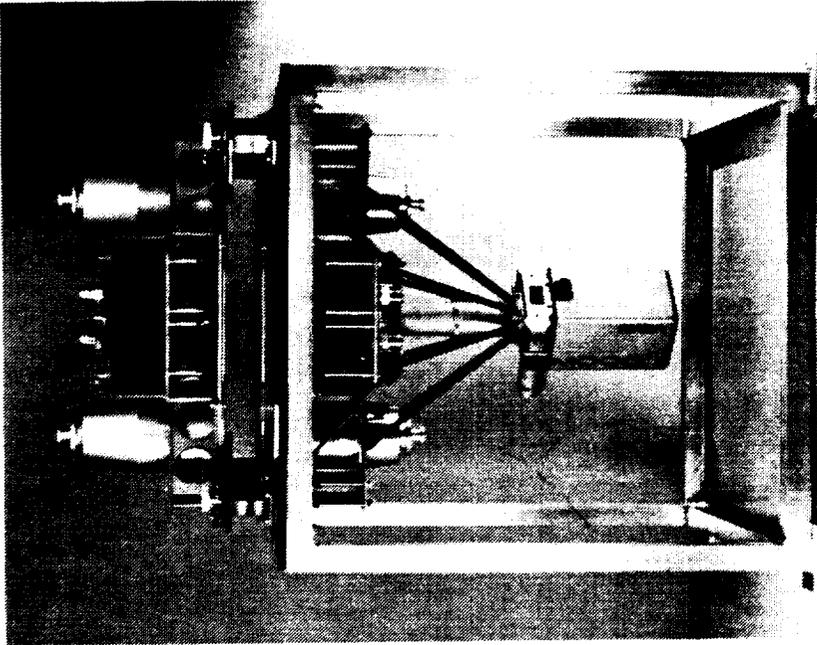
**MOOG**  
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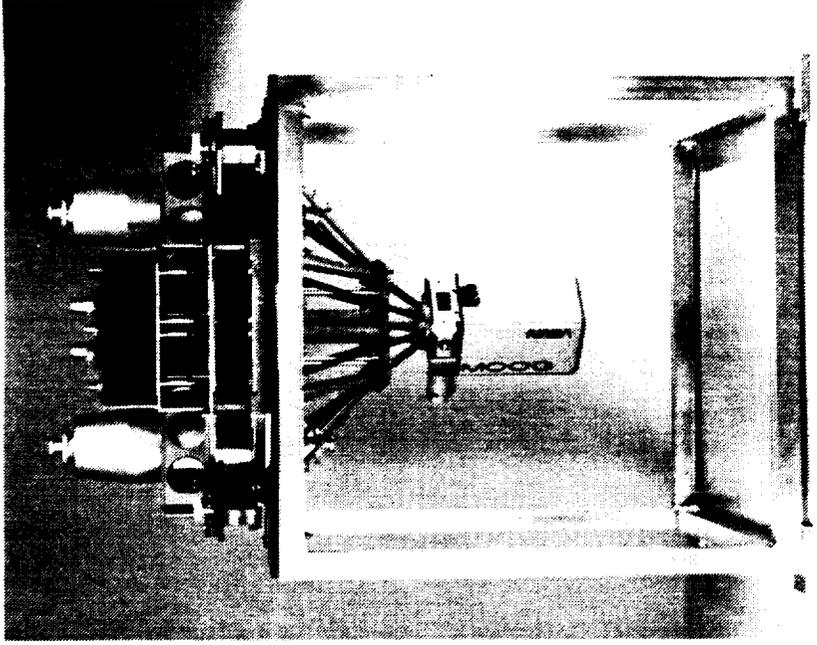
**PROGRESS STATUS AND CLOSE OUT**

- **HARDWARE SHIPPED 30 AUGUST 1990**
- **VERBAL FINAL REPORT 12 SEPTEMBER 1990**
- **DEMONSTRATION OF DELIVERABLE HARDWARE 12 SEPTEMBER 1990**
- **NARRATIVE FINAL REPORT 30 SEPTEMBER 1990**
  - **SUMMARY OF RESULTS** - **INTERFACE DESCRIPTIONS**
  - **RECOMMENDATIONS & CONCLUSIONS** - **OPERATING REQUIREMENTS/PROCEDURES**
  - **EXPERIENCE AND RESULTS OBTAINED** - **SYSTEM EVALUATION CRITERIA**
  - **PROTOTYPE AFIS DESIGN DOCUMENTATION**

NASA/MOOG AFIS



DEMATED



MATED

---

AUTOMATED FLUID INTERFACE SYSTEM

**MOOG**  
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AFIS SYSTEM COMPONENTS

- MODEL 50E629 TYPE I HALF
  - USUALLY MOUNTS ON THE TANKER SPACECRAFT
  - REQUIRES POWER AND CONTROL
  - OPERATED BY (1) MOOG MODEL 50E265 EM ACTUATOR
  - ELECTRICALLY REDUNDANT
  - CONTROL ELECTRONICS BUILT-IN
  - REDUNDANT MANUAL OVERRIDES
  - CONTAINS BULK OF COMPLEXITY AND WEIGHT
  - ACCOMODATES TANKER/SPACECRAFT MISALIGNMENTS
  - ROTARY COVER PROTECTS COUPLINGS
  
- MODEL 50E630 TYPE II HALF
  - USUALLY MOUNTS ON SPACECRAFT TO BE RESUPPLIED
  - ELECTRICALLY PASSIVE
  - SIMPLE RUGGED DESIGN
  - SMALL AND LIGHTWEIGHT
  - ROTARY COVER PROTECTS COUPLINGS
  - EASILY SCALABLE

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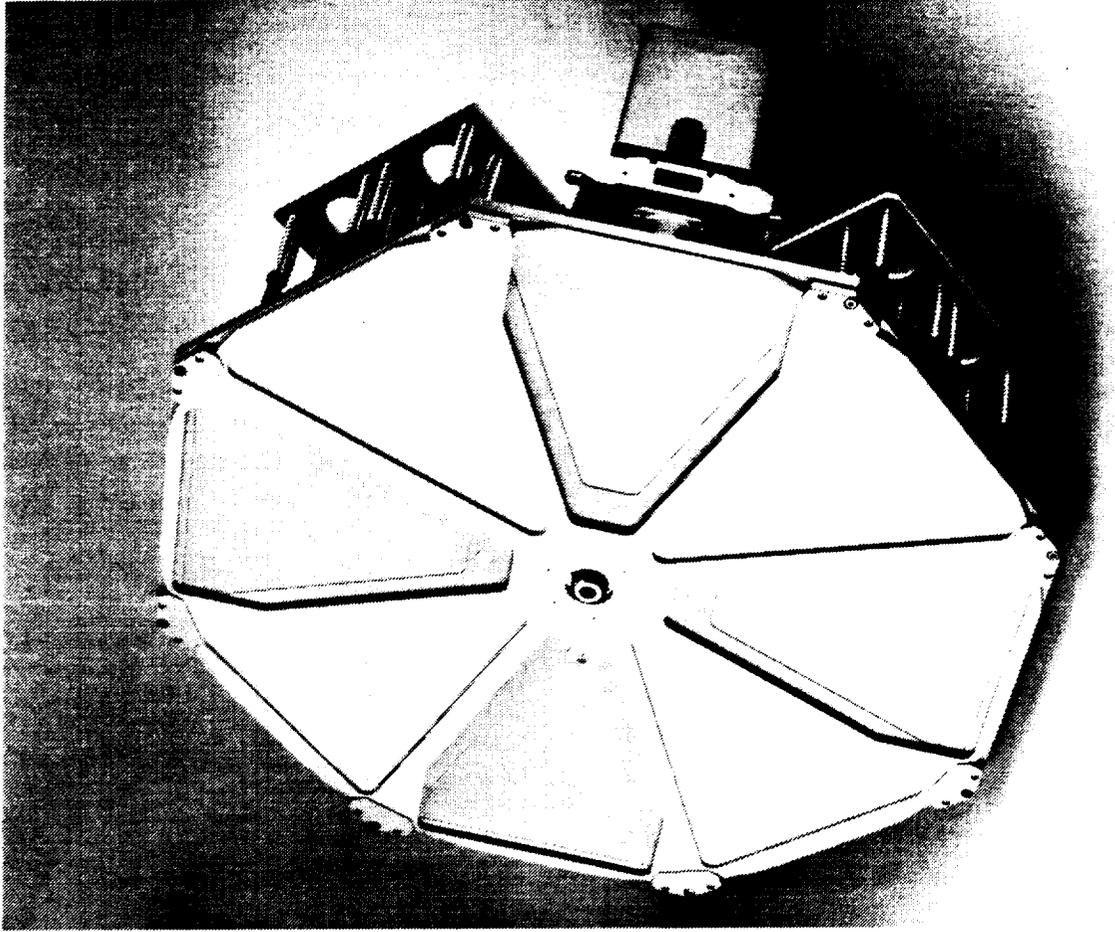
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AUTOMATED FLUID INTERFACE SYSTEM

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AFIS TYPE I HALF

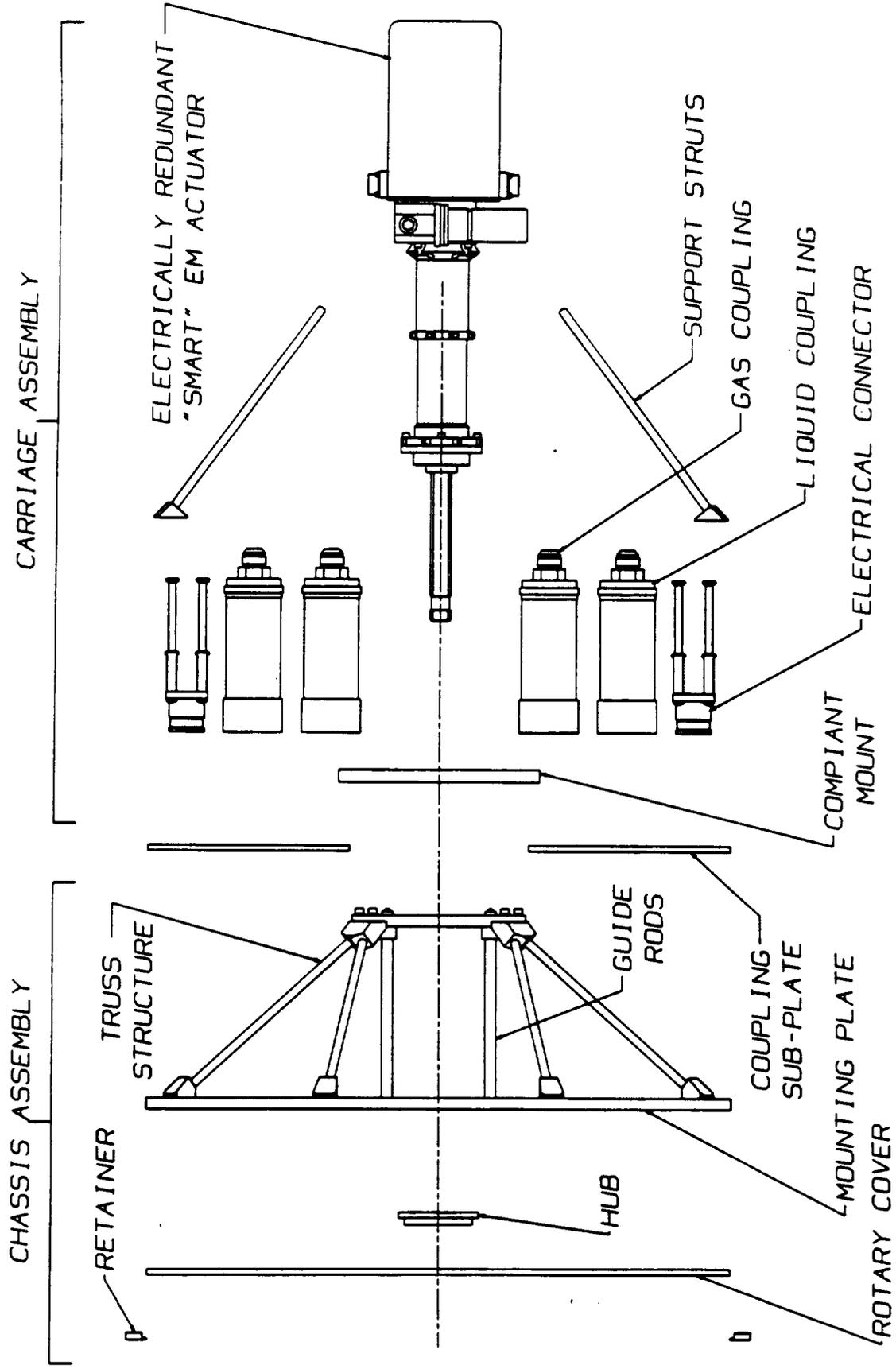


AUTOMATED FLUID INTERFACE SYSTEM

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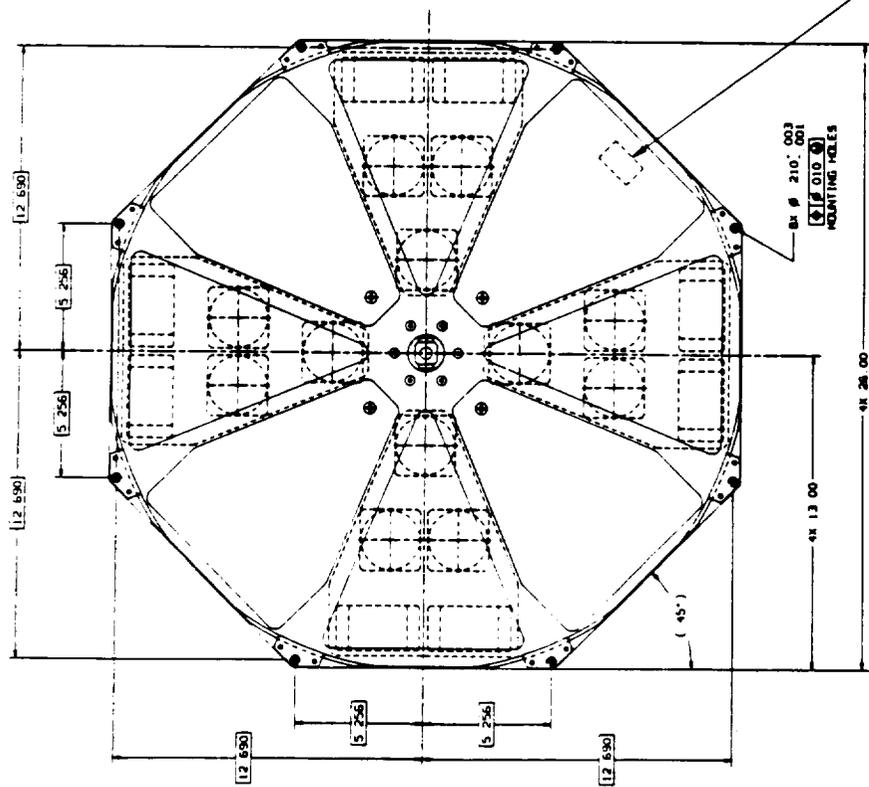
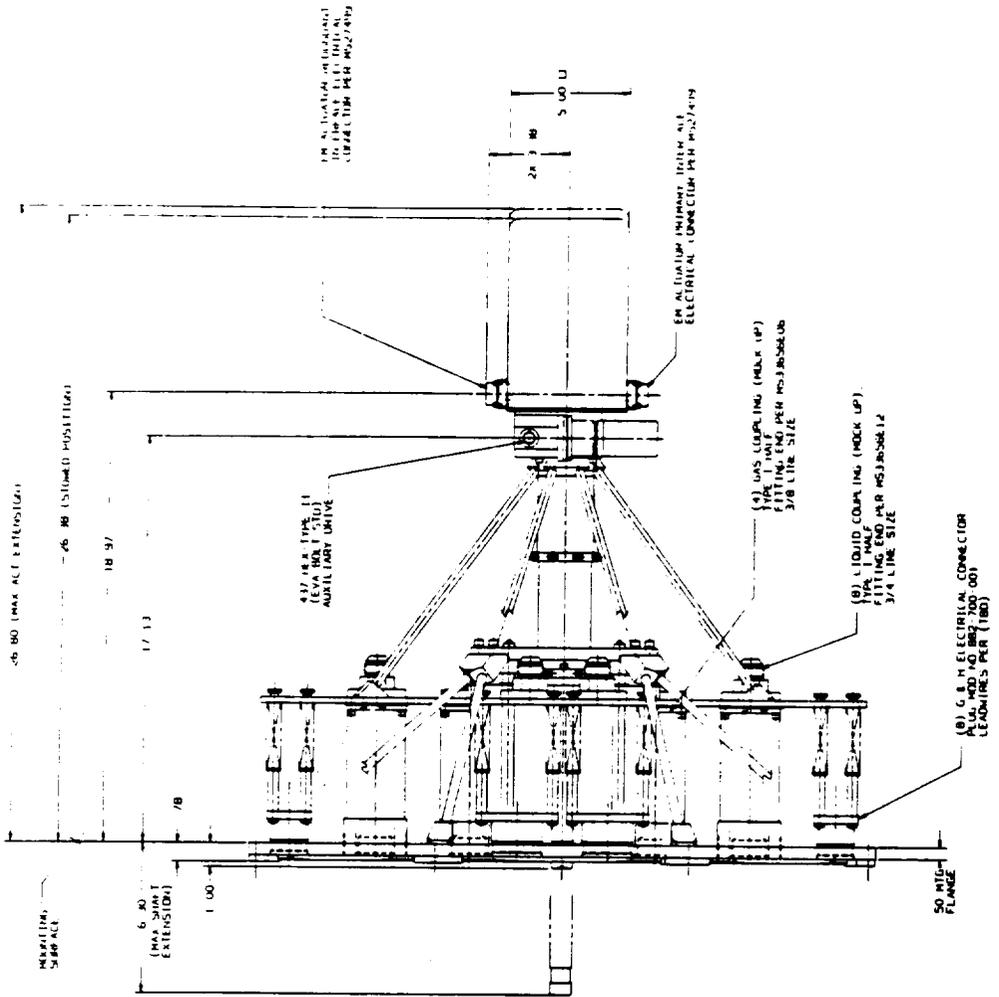
# TYPE I HALF EXPLODED



## AUTOMATED FLUID INTERFACE SYSTEM

**MOOG**  
SPACE PRODUCTS DIVISION

**NASA**  
MARSHALL SPACE FLIGHT CENTER



**MOOG**  
 SPACE MODEL IS DIVISION  
 MOOG VALVE DIVISION  
 APPROVED FLUID INTERFACE  
 PART NO. 856854-1

APPROPRIATE  
 SERIAL NO

VALVE IDENTIFICATION  
 MOOG VALVE DIVISION  
 APPROVED FLUID INTERFACE  
 PART NO. 856854-1  
 SCALE 2/1

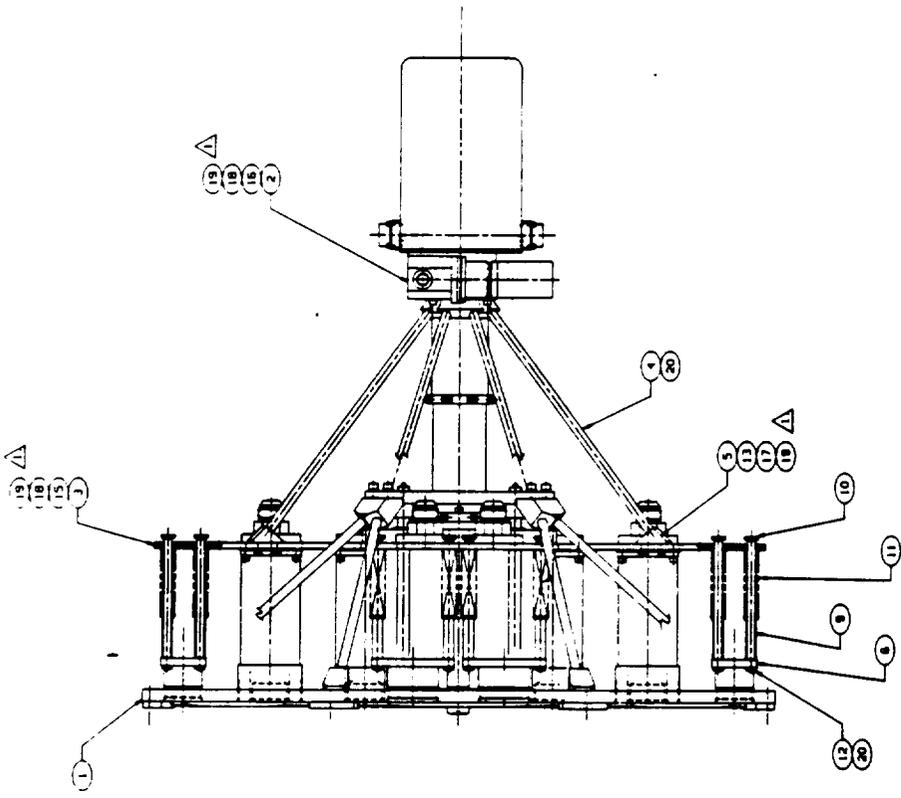
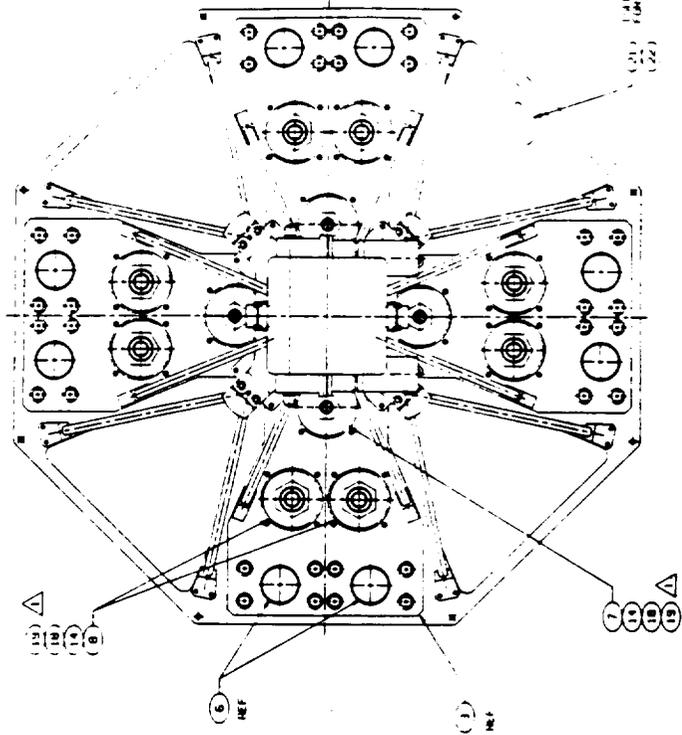
NOTES

1 MOOG PART NO 856854-1

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MOOG		TANKER HALF TYPE 1		INSTALLATION M/J 50629	
94697		856653			

11  
 1. Drawing is being furnished for information only.

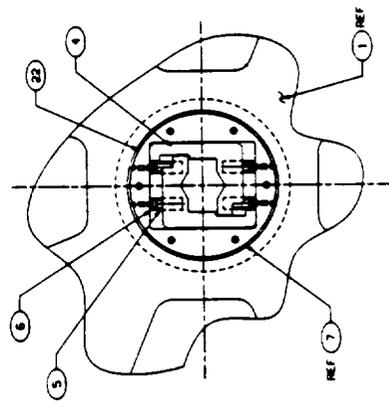
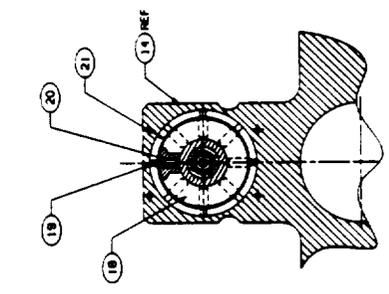
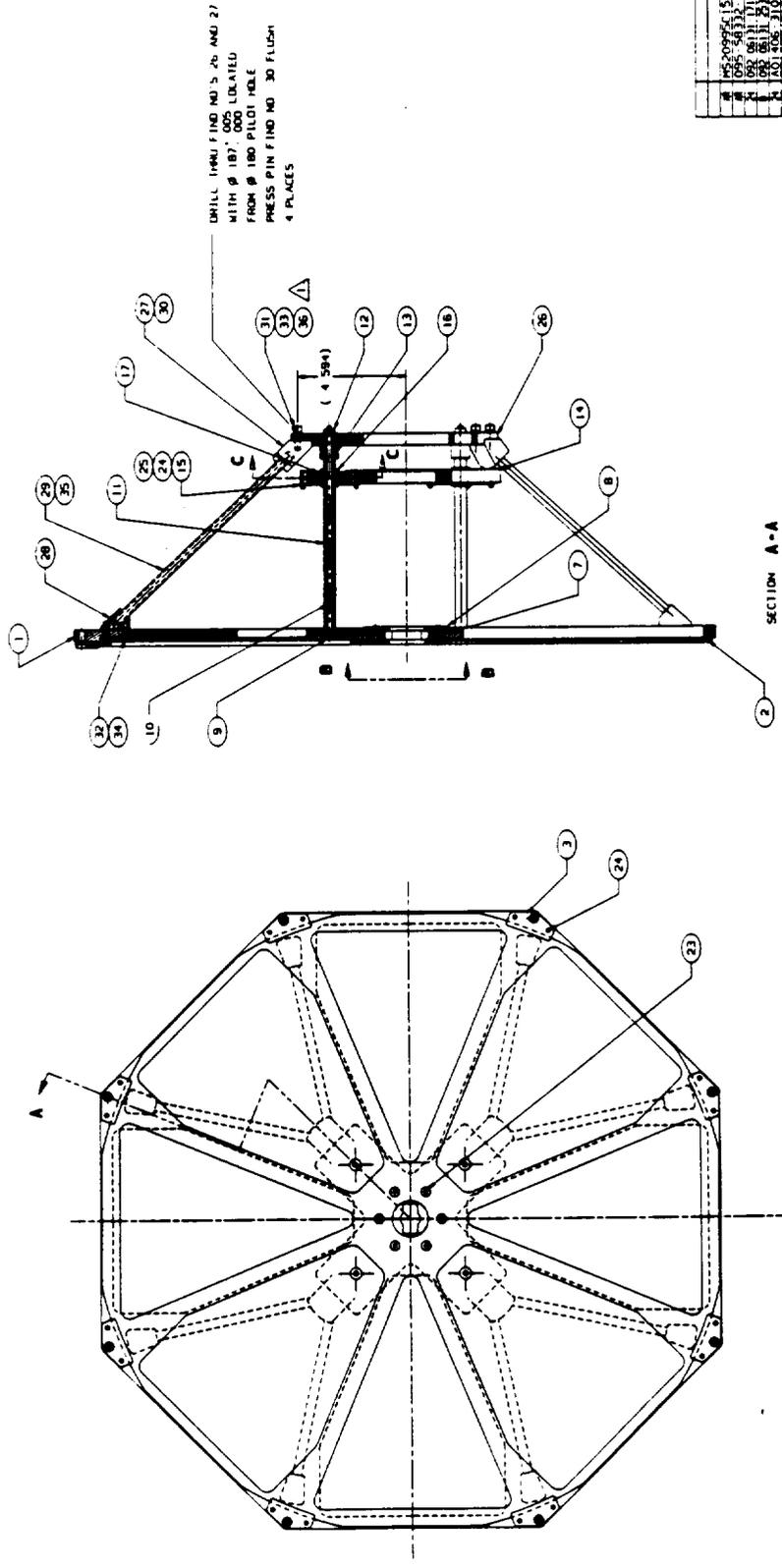


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CONTENTS (CONTINUED)	
ASSEMBLY DRAWING	1
WIRE IDENTIFICATION	2
INSTALLATION DRAWING	3
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WIRE IDENTIFICATION	100

MOOG  
 TANKER HALF TANK I  
 ASSEMBLY AND 508629  
 E 94697 850854

NOTES  
 1 SAFETY WIRE PER MS3540  
 2 PARENTHETICAL IDENTITIES ARE FOR REFERENCE ONLY



NOTES  
 1 SAFETY WIRE PER MS33540  
 2 PARALLELICAL IDENTITIES ARE FOR REFERENCE ONLY

REV	DATE	BY	CHKD	DESCRIPTION
1				ISSUE FOR MANUFACTURE
2				REVISION
3				REVISION
4				REVISION
5				REVISION
6				REVISION
7				REVISION
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9				REVISION
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31				REVISION

MOOG  
 CHASSIS TYPE I  
 ASSEMBLY PART NUMBER  
 94697  
 11-16-67  
 506 629  
 401-28-28-1

**PROPRIETARY RIGHTS**

**MOOG MODEL 50X625 ELECTROMECHANICAL ACTUATOR**

- **APPLICATION ENGINEERED VERSION OF AUC ACTUATOR DESIGNED AND BUILT UNDER MOOG IR & D**
- **INCORPORATES REDUNDANT CONTROLS AND MOTOR DRIVE ELECTRONICS DESIGNED AND BUILT UNDER MOOG IR & D**
- **ONLY INSTALLATION DRAWING WILL BE SUBMITTED TO NASA MSFC, DETAIL DRAWINGS AVAILABLE FOR REVIEW ON EYES ONLY BASIS**

**MOOG**  
SPACE PRODUCTS DIVISION

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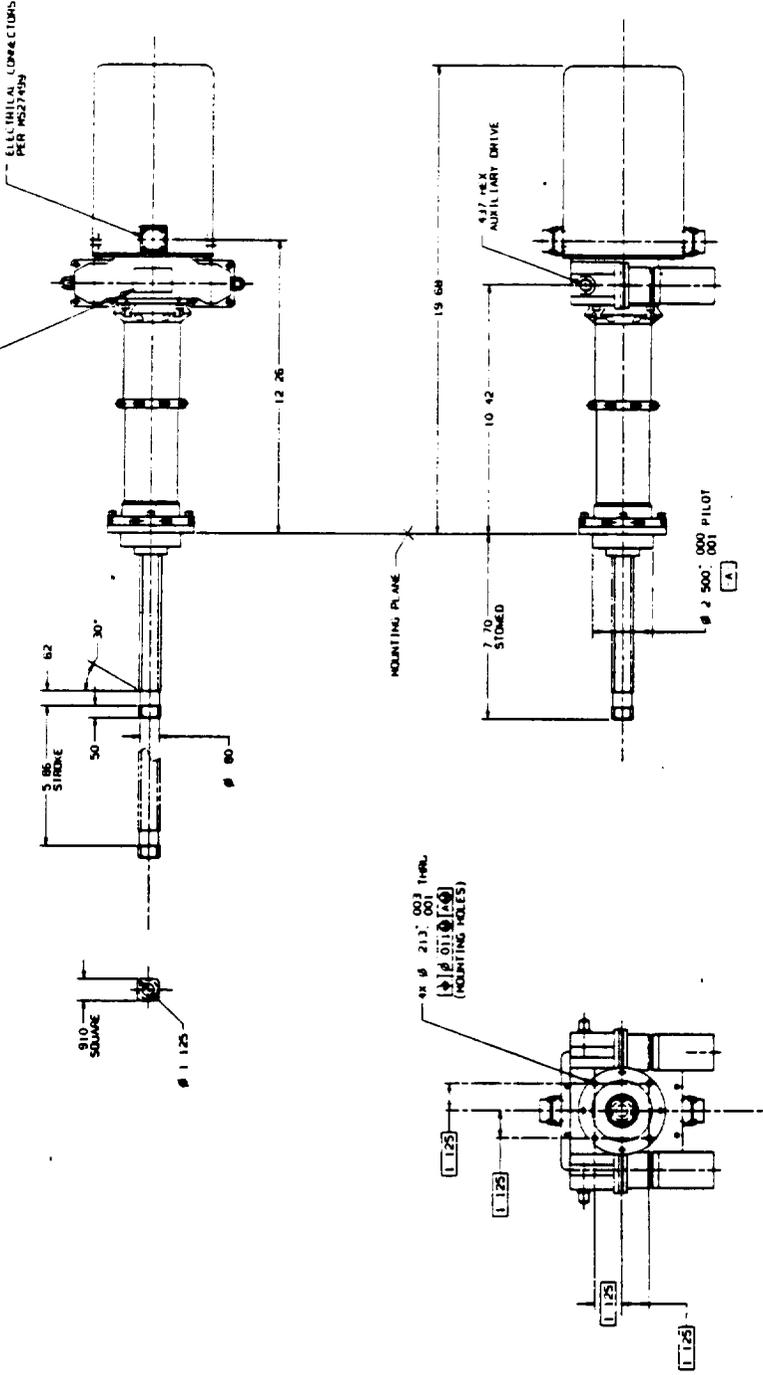
**AUTOMATED FLUID INTERFACE SYSTEM**

**NASA**  
MARSHALL SPACE FLIGHT CENTER

APPROPRIATE SERIAL NO.

MOOG VALVE INDENTIFICATION  
MOOG VALVE DIVISION  
MOORE AVIATION SYSTEMS  
11000 WILSON AVENUE  
CITY, MISSOURI 64117  
PART NO. 213-001

VALVE IDENTIFICATION  
INDENTIFIED 307 CCM  
SCALE 2:1



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NOTES

1 SYSTEM SCHEMATIC SEE MILS SYSTEM INTERCONNECT  
(FOR ACTUATOR) DIAGRAM DRAWING 856736

MOOG VALVE IDENTIFICATION INDENTIFIED 307 CCM SCALE 2:1	MOOG VALVE DIVISION MOORE AVIATION SYSTEMS 11000 WILSON AVENUE CITY, MISSOURI 64117 PART NO. 213-001	MOOG VALVE IDENTIFICATION INDENTIFIED 307 CCM SCALE 2:1	MOOG VALVE DIVISION MOORE AVIATION SYSTEMS 11000 WILSON AVENUE CITY, MISSOURI 64117 PART NO. 213-001
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MOOG  
VALVE IDENTIFICATION  
INDENTIFIED 307 CCM  
SCALE 2:1

MOOG  
VALVE DIVISION  
MOORE AVIATION SYSTEMS  
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PART NO. 213-001

MOOG  
VALVE IDENTIFICATION  
INDENTIFIED 307 CCM  
SCALE 2:1

# DC PERMANENT MAGNET GEARMOTORS

- TRW GLOBE TYPE BL PART #102A178-9
  - HIGH TEMP MOTOR COILS
  - BRAKKO 660 LUBRICANT IN GEARBOX
  - SPECIAL BRUSHES RATED FOR 1,000 HOURS VAC OPERATION
  - NO CADNIUM PLATING
  - MODIFIED OUTPUT SHAFT

	MAX CONTINUOUS	MAX REQ'D.	NO LOAD	STALL
● MOTOR SPECS (28 VDC)				
- SPEED (RPM)	6,500	6,800	8,000	0
- TORQUE (OZ-IN)	5.0	4.1	0	27
- CURRENT (AMPS)	1.4	1.2	0.25	8.9

● GEARBOX SPECS				
- OUTPUT SPEED (RPM)	126	123	145	0
- OUTPUT TORQUE (IN-LBS)	14.7	12.0	0	79

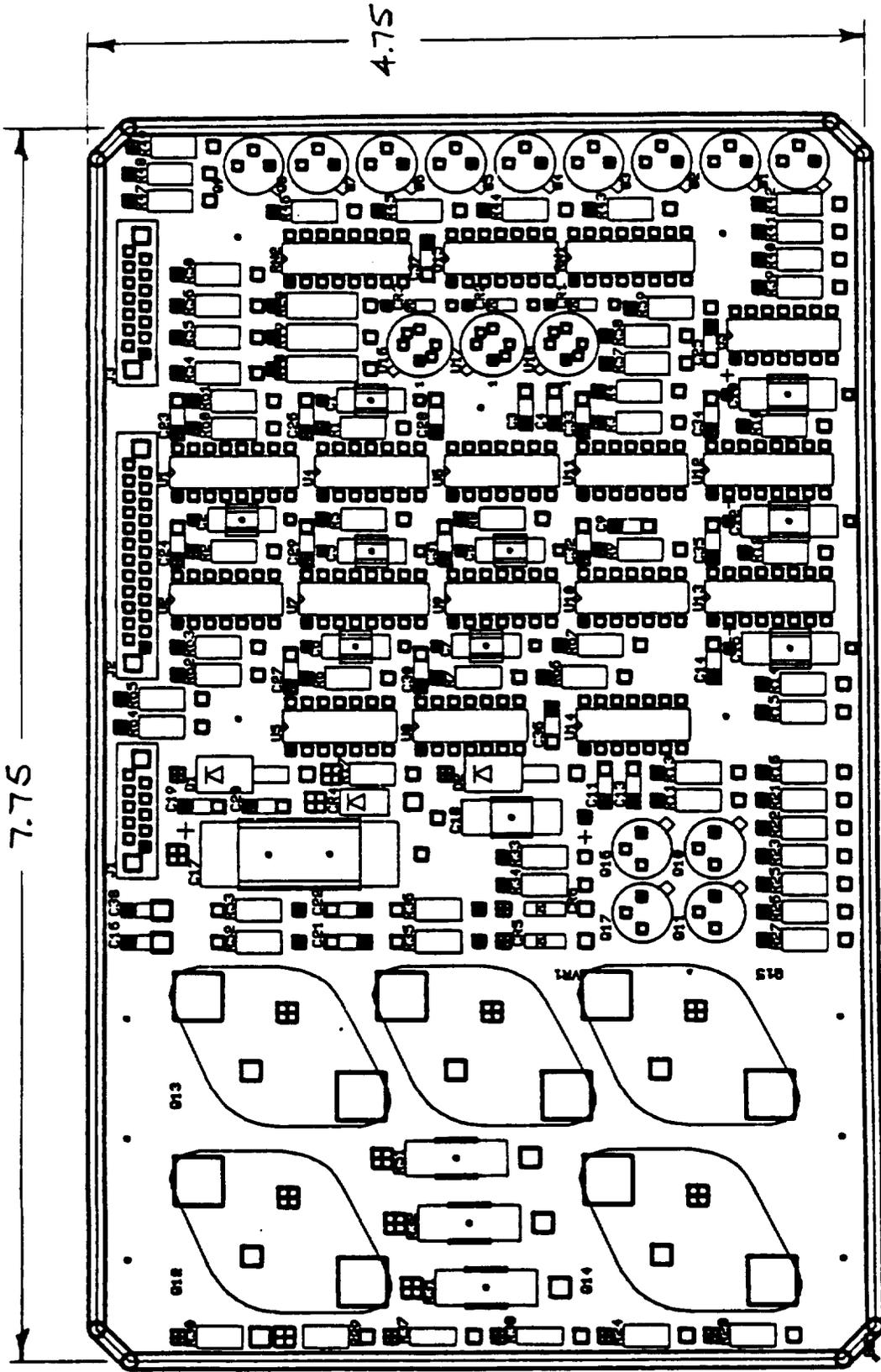
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AUTOMATED FLUID INTERFACE SYSTEM

## **"SMART ACTUATOR CONTROL DRIVE ELECTRONICS BOARD**

- **REDESIGNED DUE TO MOTOR CHANGE.**
- **ONE ENTIRE MOTOR DRIVE (LOGIC, 5 VDC POWER SUPPLY, POWER TRANSISTORS) INTEGRATED INTO EACH BOARD.**
- **NEW DESIGN HAS BEEN VERIFIED BY TESTING OF A BREADBOARDED UNIT USING AN EXISTING AUC ACTUATOR.**
- **ALL COMPONENTS ARE STANDARD AND AVAILABLE "OFF THE SHELF."**
- **ALL COMPONENTS ARE AVAILABLE IN JAN S CLASS IF REQUIRED IN FUTURE FLIGHT UNITS.**
- **DELIVERABLE PC BOARDS ARE 4 LAYER, WAVE SOLDERED PC UNITS.**
- **BOARDS ARE WELL SUPPORTED AND EASILY ACCESSIBLE FOR REMOVAL/INSTALLATION OR TESTING IN PLACE.**
- **BORDS ARE THERMALLY PROTECTED BY HEAT SINKING AND REDUNDANT HEATERS**

# "SMART" ACTUATOR CONTROL DRIVE ELECTRONICS BOARD



AUTOMATED FLUID INTERFACE SYSTEM

**MOOG**  
SPACE PRODUCTS DIVISION

**NASA**  
MARSHALL SPACE FLIGHT CENTER

**POWER AND CONTROL REQUIREMENTS**

● **POWER (WATTS @ 28 VDC):**

	<b><u>PEAK</u></b>	<b><u>AVERAGE</u></b>
- ENGAGING/DISENGAGING	34	28
- STANDBY	5	5
- HEATERS (SEPARTE SOURCE)	10	1

● **CONTROL (5 VDC CONTINUOUS INPUT SIGNAL)**

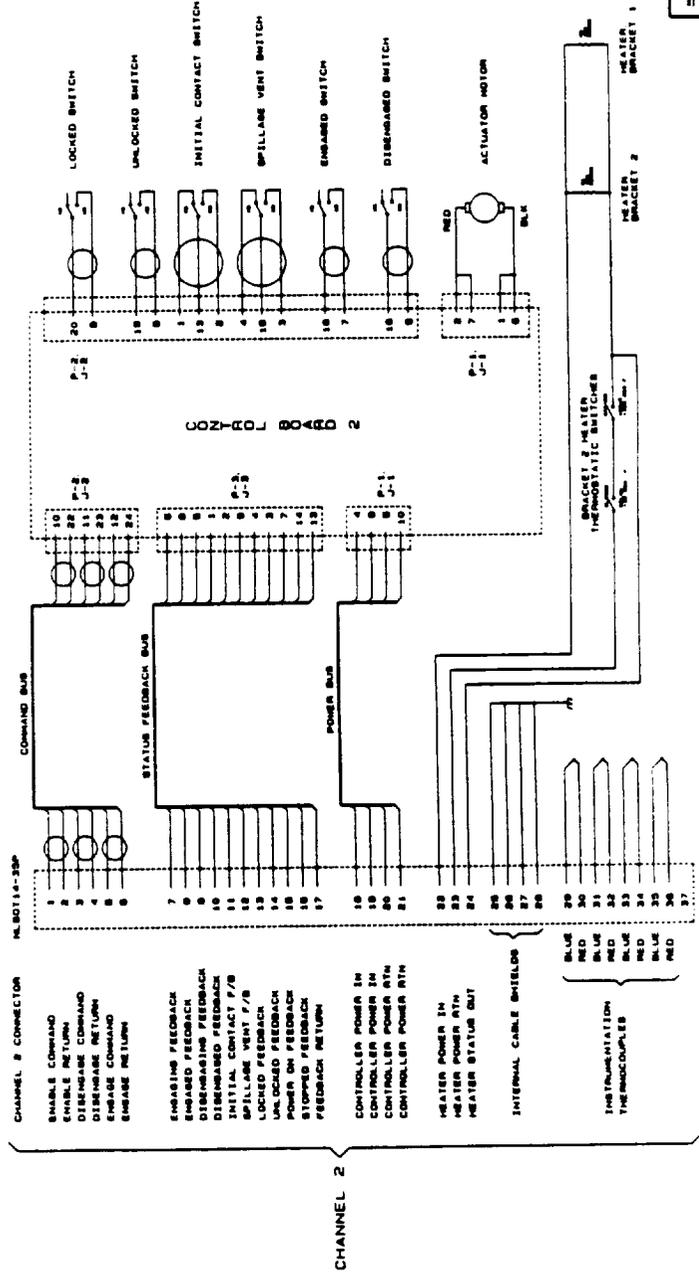
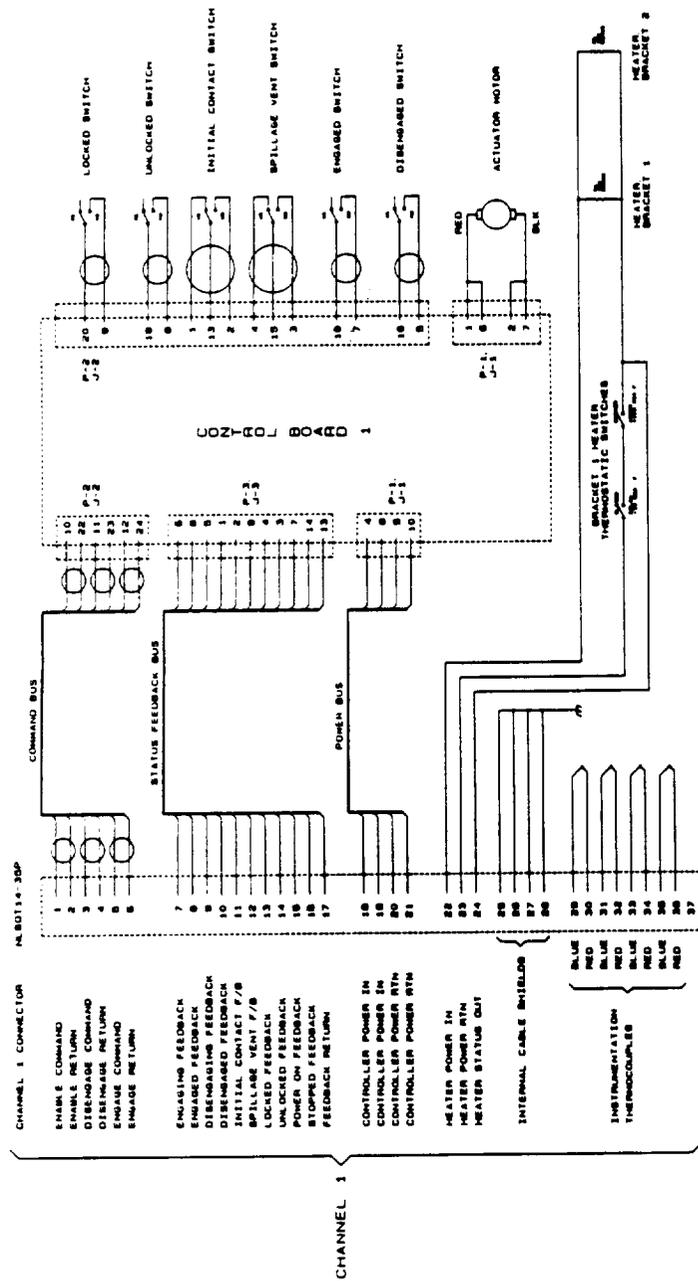
- "ENGAGE"
- "DISENGAGE"
- "ENABLE/RESET" (ABSENCE = "STOP")

---

AUTOMATED FLUID INTERFACE SYSTEM

## OUTPUT DATA

- STATUS SIGNALS (5 VDC BINARY OUTPUT SIGNAL)
  - "ENGAGED" - "LOCKED"
  - "DISENGAGED" - "UNLOCKED"
  - "STOPPED" - "ENGAGEMENT IN PROCESS"
  - "SPILLAGE VENT" - "DISENGAGEMENT IN PROGRESS"
  - "INITIAL CONTACT" - "HEATERS ON"
  
- TEMPERATURE SENSORS (ANALOG THERMOCOUPLE SIGNALS)
  - MOTOR - IC CHIP FIELD
  - HEATER -POWER TRANSISTORS



- NOTES**
- 1 CIRCLED WIRE GROUPS REPRESENT INDIVIDUAL PAIRS OR TRIPLES
  - 2 WIRE SHOWN AS BUBBLE REPRESENT INDIVIDUAL WIRE BUNDLES
  - 3 USE 24 GAUGE WIRE FOR ALL SIGNAL WIRING HEATER WIRING MAY ALSO BE 24 GAUGE
  - 4 POWER WIRING IS 22 GAUGE THIS INCLUDES THE MOTOR OUTPUT WIRING
  - 5 WIRE TYPE SHALL BE (TMO)
  - 6 ALL CRIMP CONNECTIONS SHALL BE PER MIL - 1700
  - 7 ALL SOLDERED CONNECTIONS SHALL BE PER MIL - STD - 454

**MOOG**

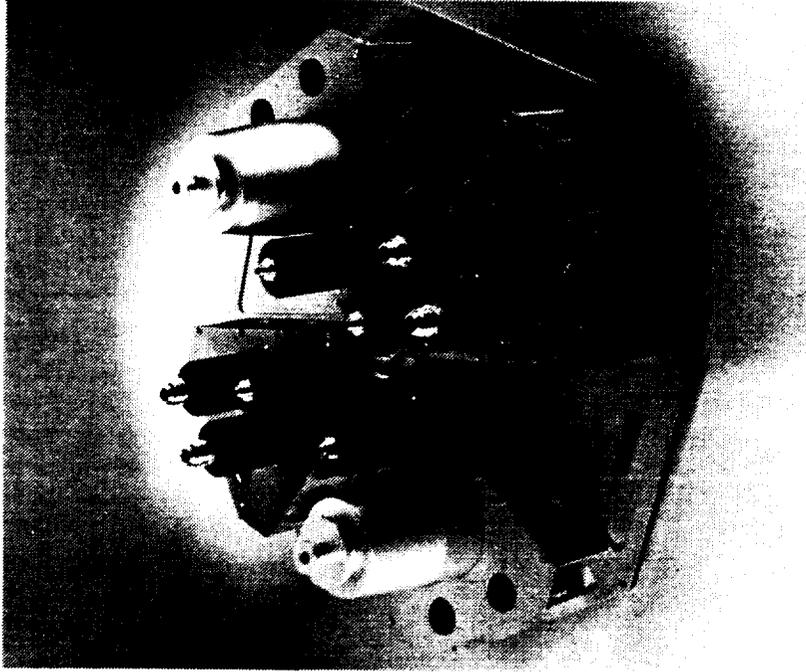
MOOG VALVE DIVISION  
 14600 E. SPRING STREET  
 AUSTIN, TEXAS 78761  
 TELEPHONE (512) 799-7000  
 CABLE MOOGTX  
 FAX (512) 799-7000

DATE: 08/08/80  
 BY: 08/08/80  
 456 NOTES  
 CONNECT WIRING FOR SWITCH SWAP

94697

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AFIS TYPE II HALF



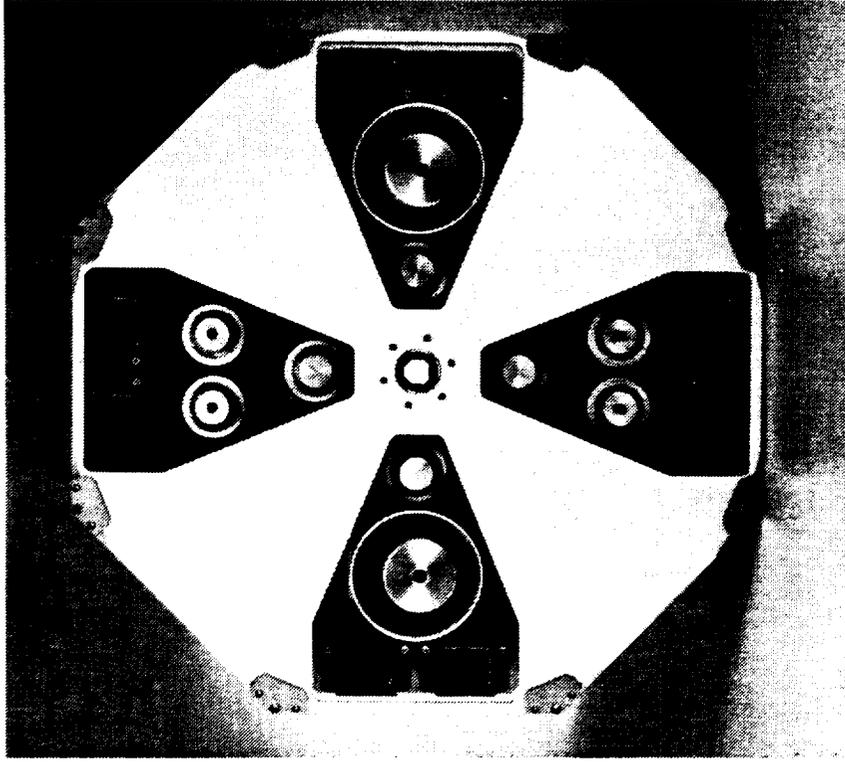
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**AUTOMATED FLUID INTERFACE SYSTEM**

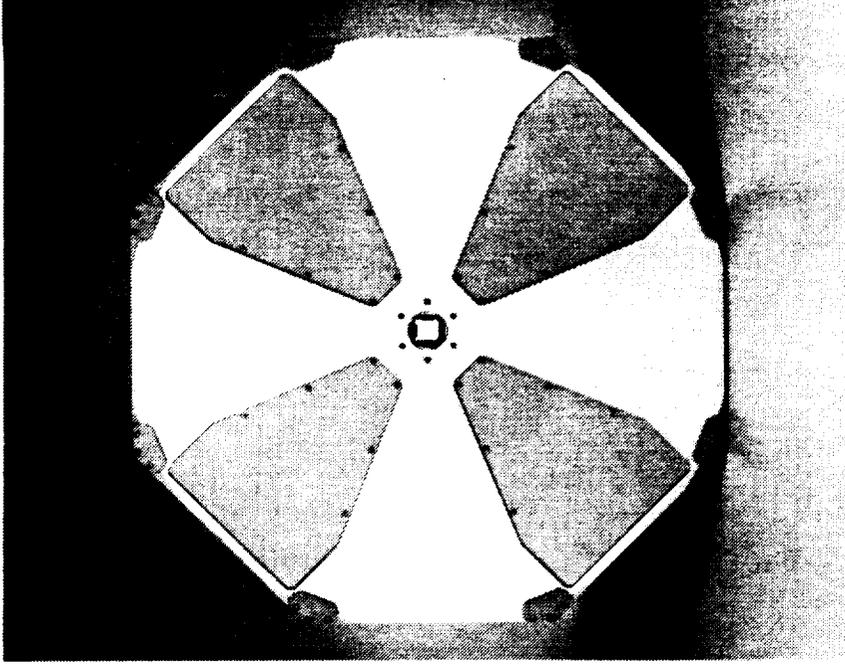
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SPACE PRODUCTS DIVISION

**NASA**  
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ROTARY COVERS PROTECT COUPLINGS



OPEN



CLOSED

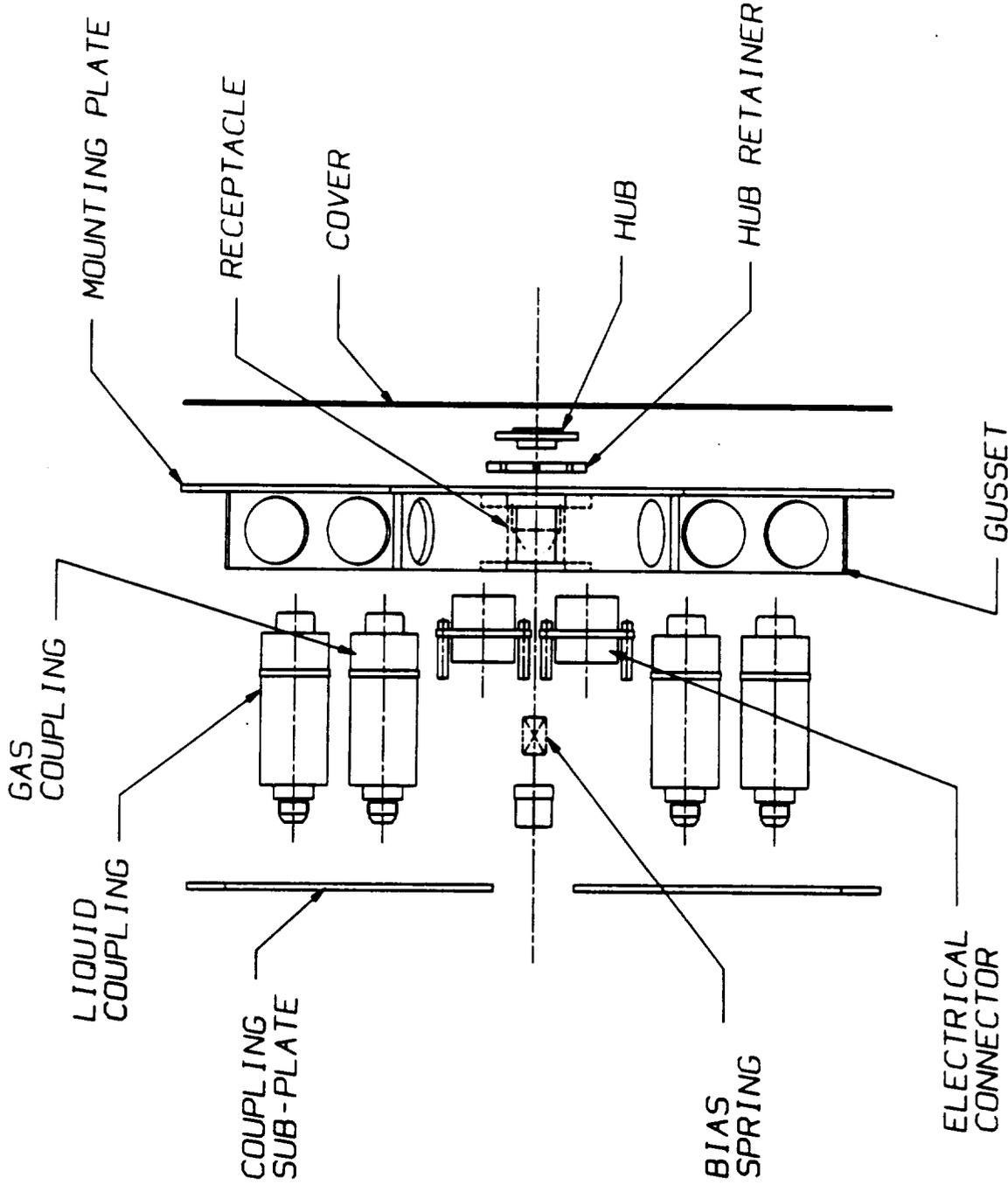
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AUTOMATED FLUID INTERFACE SYSTEM

**MOOG**  
SPACE PRODUCTS DIVISION

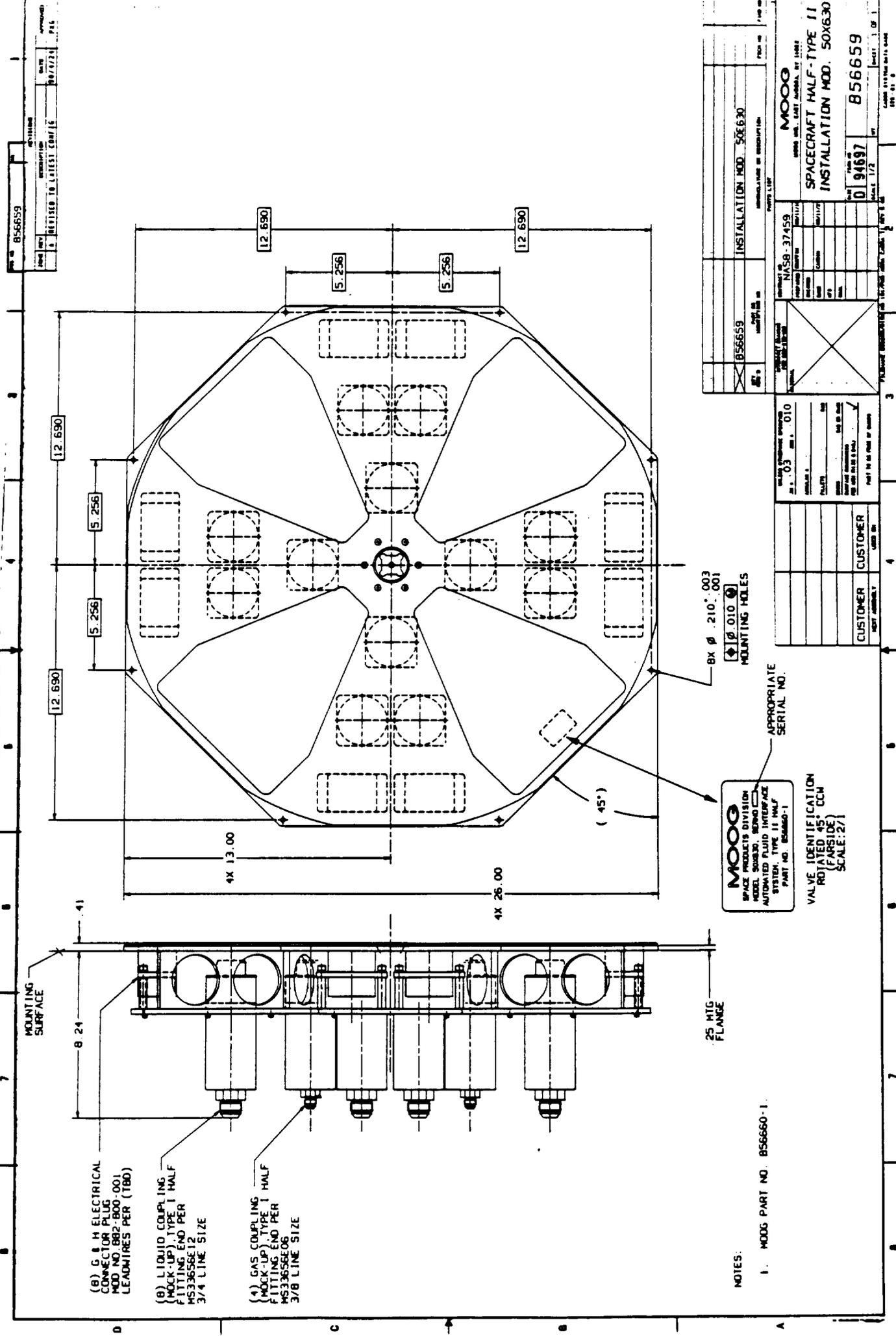
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# TYPE II HALF EXPLODED



AUTOMATED FLUID INTERFACE SYSTEM

24



MOOG PART NO. 856659	REV. 1	REVISED TO LATEST CHANGE	DATE 06/07/81	APPROVED
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MOOG	MOOG
SPACECRAFT HALF-TYPE II	SPACECRAFT HALF-TYPE II
INSTALLATION MOD. 50X630	INSTALLATION MOD. 50X630
MOOG PART NO. 856659	MOOG PART NO. 856659
REV. 1	REV. 1
DATE 06/07/81	DATE 06/07/81

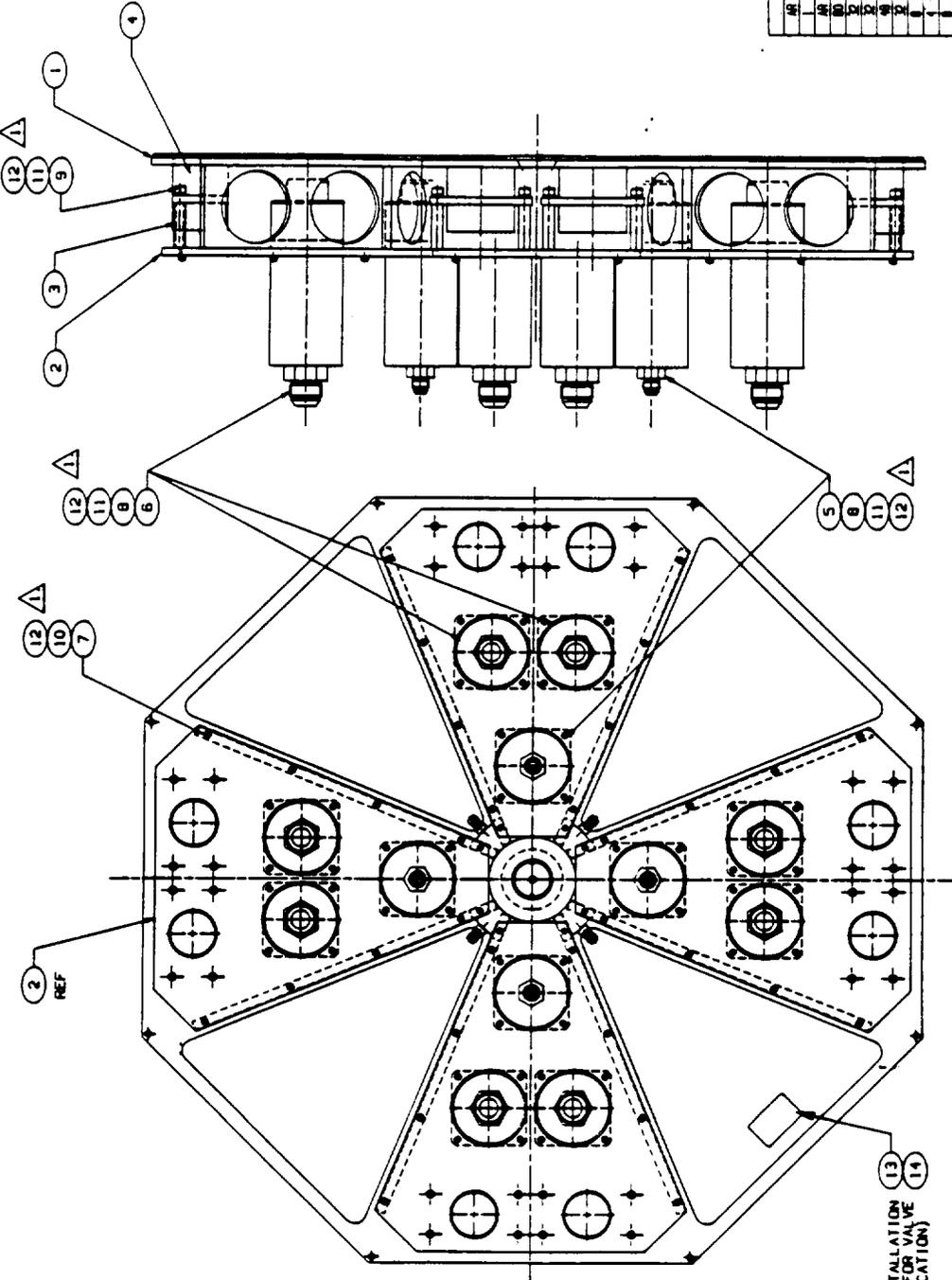
MOOG	MOOG
SPACE PRODUCTS DIVISION	SPACE PRODUCTS DIVISION
MODEL 50030; SERVO	MODEL 50030; SERVO
AUTOMATED FLUID INTERFACE SYSTEM, TYPE II HALF	AUTOMATED FLUID INTERFACE SYSTEM, TYPE II HALF
PART NO. 856660-1	PART NO. 856660-1
VALVE IDENTIFICATION	VALVE IDENTIFICATION
ROTATED 45° CCM	ROTATED 45° CCM
(FARSIDE)	(FARSIDE)
SCALE: 2/1	SCALE: 2/1

MOOG	MOOG
SPACE PRODUCTS DIVISION	SPACE PRODUCTS DIVISION
MODEL 50030; SERVO	MODEL 50030; SERVO
AUTOMATED FLUID INTERFACE SYSTEM, TYPE II HALF	AUTOMATED FLUID INTERFACE SYSTEM, TYPE II HALF
PART NO. 856660-1	PART NO. 856660-1
VALVE IDENTIFICATION	VALVE IDENTIFICATION
ROTATED 45° CCM	ROTATED 45° CCM
(FARSIDE)	(FARSIDE)
SCALE: 2/1	SCALE: 2/1

NOTES:

- MOOG PART NO. 856660-1.

REVISED TO LATEST CONFIG	
DATE	APPROVED
08/17/24	P.L.G.



(SEE INSTALLATION DRAWING FOR VALVE IDENTIFICATION)

NOTES:

1 SAFETY WIRE PER MS33540.

2 PARENTHETICAL IDENTITIES ARE FOR REFERENCE ONLY.

ITEM NO.	DESCRIPTION	QTY	UNIT
1	COATING COMPOUND		
2	NAME PLATE		
3	LOCKWIRE (MS20995C15)		
4	WASHER FLAT		
5	WASHER FLAT		
6	SCREW SOC HD CAP (090-42559C0304034P)		
7	SCREW SOC HD CAP		
8	SCREW SOC HD CAP		
9	SCREW SOC HD CAP		
10	SCREW SOC HD CAP		
11	SCREW SOC HD CAP		
12	SCREW SOC HD CAP		
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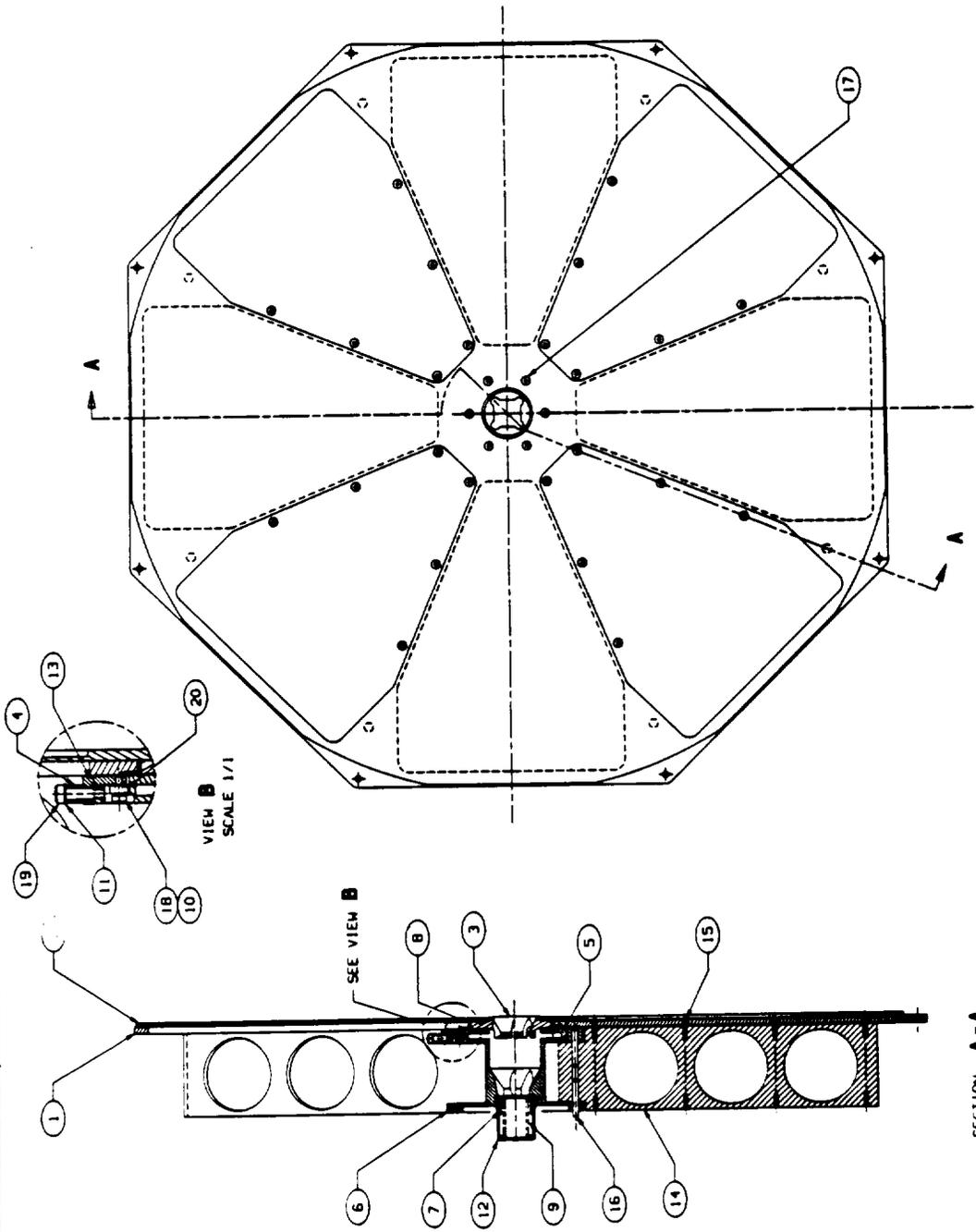
MOOG	
SPACECRAFT HALF-TYPE II	
ASSEMBLY MOD. 50X630	
DATE	09/17/24
REV	0
QTY	1
ASSEMBLY	ASSEMBLY

CUSTOMER	

MOOG	
SPACECRAFT HALF-TYPE II	
ASSEMBLY MOD. 50X630	
DATE	09/17/24
REV	0
QTY	1
ASSEMBLY	ASSEMBLY

26

Part No.	B56658
Rev.	1
Released by	REVISIONS TO LATEST CONFIG
Date	10/14/73
Page	1 of 1



SECTION A-A

- NOTES:
1. PARENTHETICAL IDENTITIES ARE FOR REFERENCE ONLY.
  2. VENDOR ITEM, SEE SPECIFICATION CONTROL DRAWING.

20	BEARING, BALL	29440
19	SCREW SHOULDER, SOC HD	00141
18	SCREW SHOULDER, SOC HD	00141
17	SCREW SOC HD FLAT	00141
16	PIN DOWEL (093-51745-340)	
15	SCREW SOC HD FLAT	
14	SCREW SOC HD FLAT	
13	GUSSET, SUPPORT	
12	SLIDE COVER DETENT	
11	RETAINER SPRING SEAT	
10	WASHER FLAT (092-45353-0101)	
9	WASHER FLAT (092-45353-0004L)	
8	SPRING COIL, METAL	
7	PLATE, MOUNTING, TYPE II	
6	PLATE, COVER, TYPE II	
5	PLATE, COVER, TYPE II	
4	ASSEMBLY	

MOOG	CHASSIS TYPE II	ASSEMBLY MOD 50X630
Part No.	94697	B56658
Scale	1:1	
Sheet	1 of 1	

Part No.	50X630
Rev.	1
Released by	
Date	
Page	

## ACTUAL WEIGHTS

(LBM)	AFIS ONLY	WITH CONNECTOR MOCK-UPS		
		BI-PROP	MONOPROP	CRYOGENIC
Type I (Tanker) Half	36.6	70.6	67.2	73.4
Type II (Spacecraft) Half	17.2	48.8	45.6	62.4
Total	53.8	119.4	112.8	135.8

- CARRIES UP TO 1 1/2 TIMES ITS OWN WEIGHT IN COUPLINGS.
- WEIGHT BIASED 2:1 AWAY FROM SPACECRAFT HALF.
- FLEX HOSES AND ELECTRICAL CABLES NOT INCLUDED.

---

AUTOMATED FLUID INTERFACE SYSTEM

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## MATERIAL SELECTION SUMMARY

MATERIAL	USE	SURFACE TREATMENT
Aluminum Alloy 6061-T6 or T651 Per QQ-A-200/8 or QQ-A-225/8 or QQ-A-250/11 or QQ-A-200/11	Actuator Housing, Components	<ul style="list-style-type: none"> <li>● Anodize per MIL-A-8625 Type II, Class 1 or Class 2</li> <li>● Zinc Chromate Primer per TT-P-1757 (Threaded insert holes)</li> <li>● Hard Anodize per MIL-A-8635, Type III, Class I (Hot Water Sealed)</li> <li>● Electrofilm 92109 per MIL-L-46010 (MOS<sub>2</sub> Molydisulfide Dry Film Lube)</li> </ul>
Bronze per MIL-B-994	Worm Gear	Nickel Plate per MIL-C-26074 (.0003 to .0005 THN)
CRES 303 per ASTM A582	Worm, Shoulder Screw	<ul style="list-style-type: none"> <li>● Electrofilm (2109) per MIL-L-46010 (MOS<sub>2</sub> Molydisulfide Dry Film Lube)</li> <li>● Passivate per QQ-P-35</li> </ul>
CRES, Type 15-5 PH per AMS-5659 Heat Treat per MIL-H-6875, Cond H1075 or H1025	Drive Shaft, Thrust Washer, Actuator Shaft, Rollers, Rod	<ul style="list-style-type: none"> <li>● Passivate per QQ-P-35</li> <li>● Titanium Nitride Coating per EP3566</li> </ul>
Teflon TFE per AMS-3651	Glide Ring	N/A
Teflon TFE per AMS-3756 (75% PTFE/25% Glass)	Journal Bearings, Washers	N/A
CRES, Type 302 or 316 per QQ-S-763 or QQ-S-766	Spacer, Cam	Passivate per QQ-P-35
CRES, Type 17-7PH, Condition C per AMS-5673 or AMS-5678 Heat Treat to CH900 per MIL-H-6875.	Springs	Finish Process per EP 3204
CRES A-286	Fasteners, Clinch Nuts	Silver Plate
Aluminum Bronze per AMS-4635	Journal Bearings, Index Bushing	N/A

### AUTOMATED FLUID INTERFACE SYSTEM

# MATERIAL SELECTION SUMMARY

MATERIAL	USE	SURFACE TREATMENT
Fiber, Commercial, Blank Vulcanized per MIL-F-1148A Change CH	Washers Washers	N/A
Brass Alloy, Type 377 per QQ-S-626	Shear Pin	N/A
Threaded Locking Compound per MIL-S-46163 Type II or M	Thread Locking	N/A
CRES per FF-S-86	Capscrews	Passivate per QQ-P-35
Copper Alloy per MIL-W-81044/B	Wire	Silver Coated
Solder per QQ-S-571	Solder	N/A
Tefzel (Dupont ETFE Floropolmar)	Cable Tie	N/A
Irradiated Polyolefin Tubing per MIL-R-46846 Type V and MIL-K-817	Shrink Tubing	N/A
Epoxy	Attach Nameplate	N/A
Aluminum Tooling Plate (MIC6)	Sub-Plates, Structure, Covers	<ul style="list-style-type: none"> <li>● Anodize per MIL-A-8625 Type II, Class 2</li> <li>● Zinc Chromate Primer per TT-P-1757 (Threaded insert holes)</li> </ul>
Teflon (TFF) per MIL-R-8791	Glide Ring, Compliant Joint Bearing	N/A
CRES 18-8 (Type 302/304) per AMS-7245	Threaded Inserts	N/A
CRES 440C	Ball Bearing	N/A
G10 Glass Epoxy	Insulators	N/A

**NOTE:**

- 1) Motor and electronics materials not representative of flight unit thus not included here. All materials used are compatible with thermal vacuum ground testing.

---

## AUTOMATED FLUID INTERFACE SYSTEM

## TANKER/SPACECRAFT SIMULATOR

- **FRAME**
  - SIMULATES TANKER/SPACECRAFT STRUCTURES
  - SIMULATES DOCKING MECHANISM
  - ADJUSTABLE TANKER/SPACECRAFT MISALIGNMENT
  
- **CONTROL BOX**
  - MANUAL INTERFACE FOR AFIS
  - INPUT/OUTPUT VISUAL INDICATORS
  - FEEDTHROUGH FOR REMOTE CONTROL
  - SIMULATES TANKER POWER BUS
  - (2) REMOTE EMERGENCY STOP BUTTONS PROVIDED FOR SAFETY
  
- **FLEX HOLES**
  - FOR LIQUID AND GAS COUPLING MOCK-UPS
  - ADDRESS INDUCED LOADING ISSUE
  - DEMONSTRATES POTENTIAL ROUTING SCHEMES

---

AUTOMATED FLUID INTERFACE SYSTEM

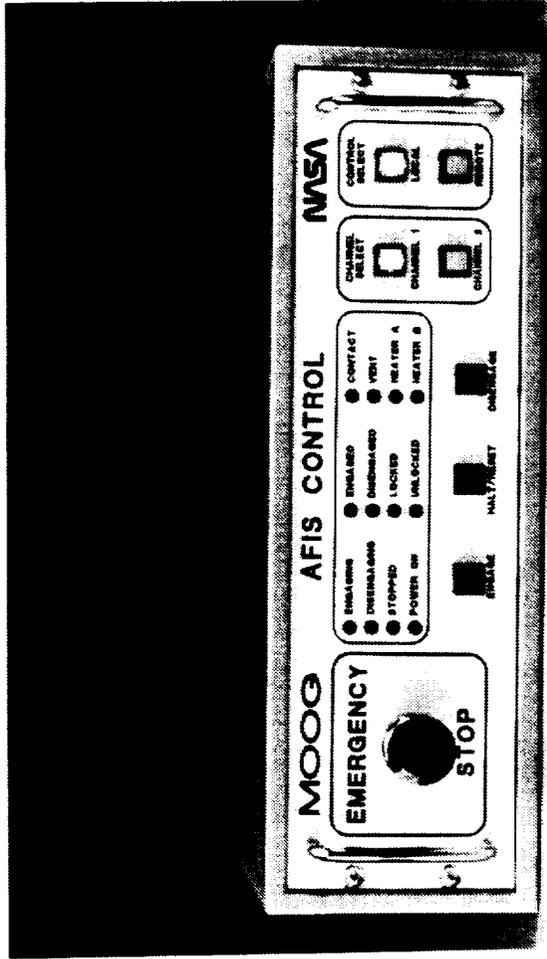
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# AFIS CONTROL BOX



## AUTOMATED FLUID INTERFACE SYSTEM

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**FUNCTIONAL DESCRIPTION: TANKER/SPACECRAFT DOCKING**

- **AFIS IS POWERED DOWN AND PASSIVE**
- **NO PHYSICAL CONTACT DURING DOCKING**
- **2.2" MINIMUM CLEARANCE BETWEEN AFIS HALVES**
- **DOCKING MECHANISM POSITIONS AFIS WITHIN MISALIGNMENT ENVELOPE:  
± .025° ANGULAR  
± 0.10" X, Y, Z OFFSET  
± 0.40° ROTARY**

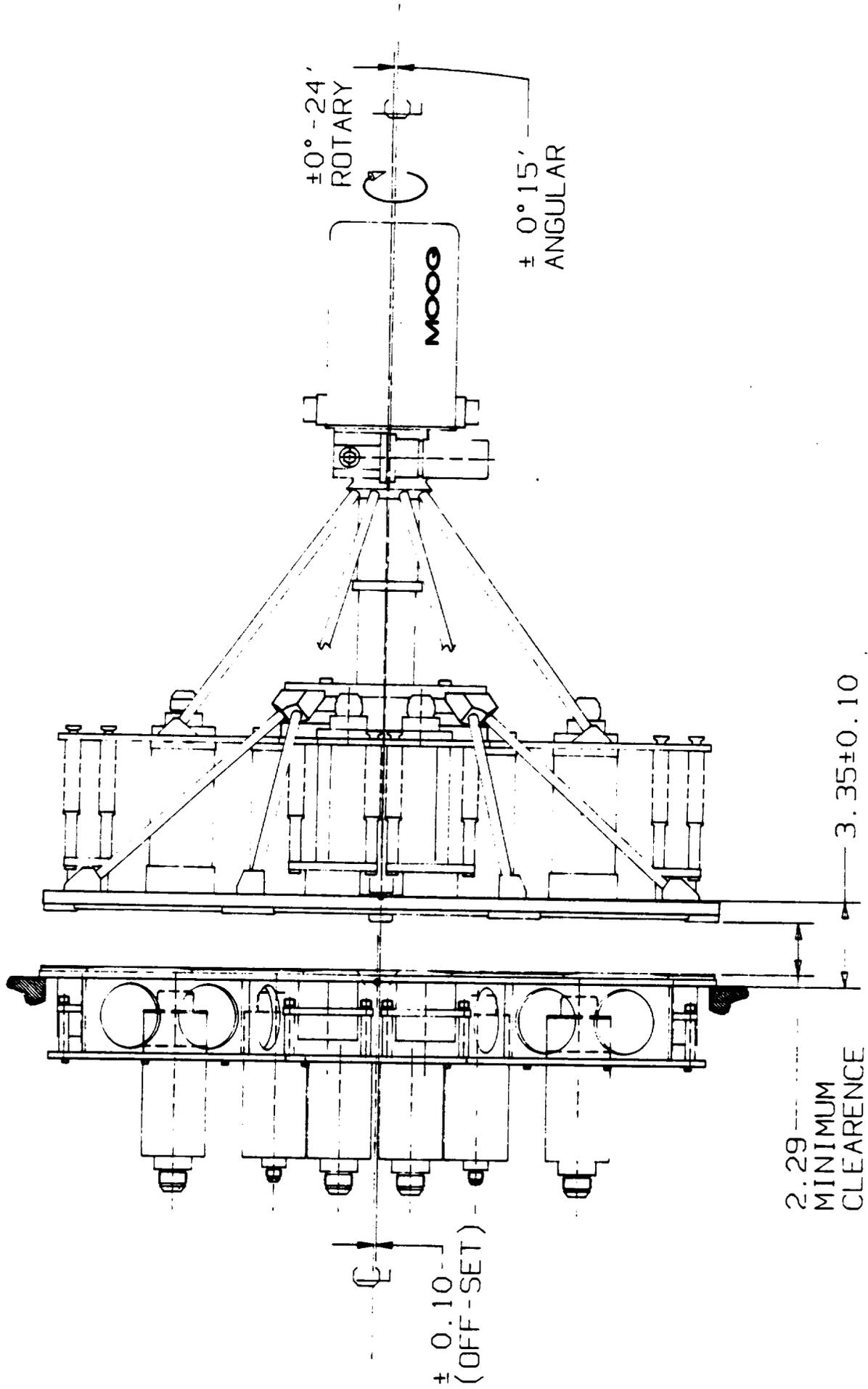
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**AUTOMATED FLUID INTERFACE SYSTEM**

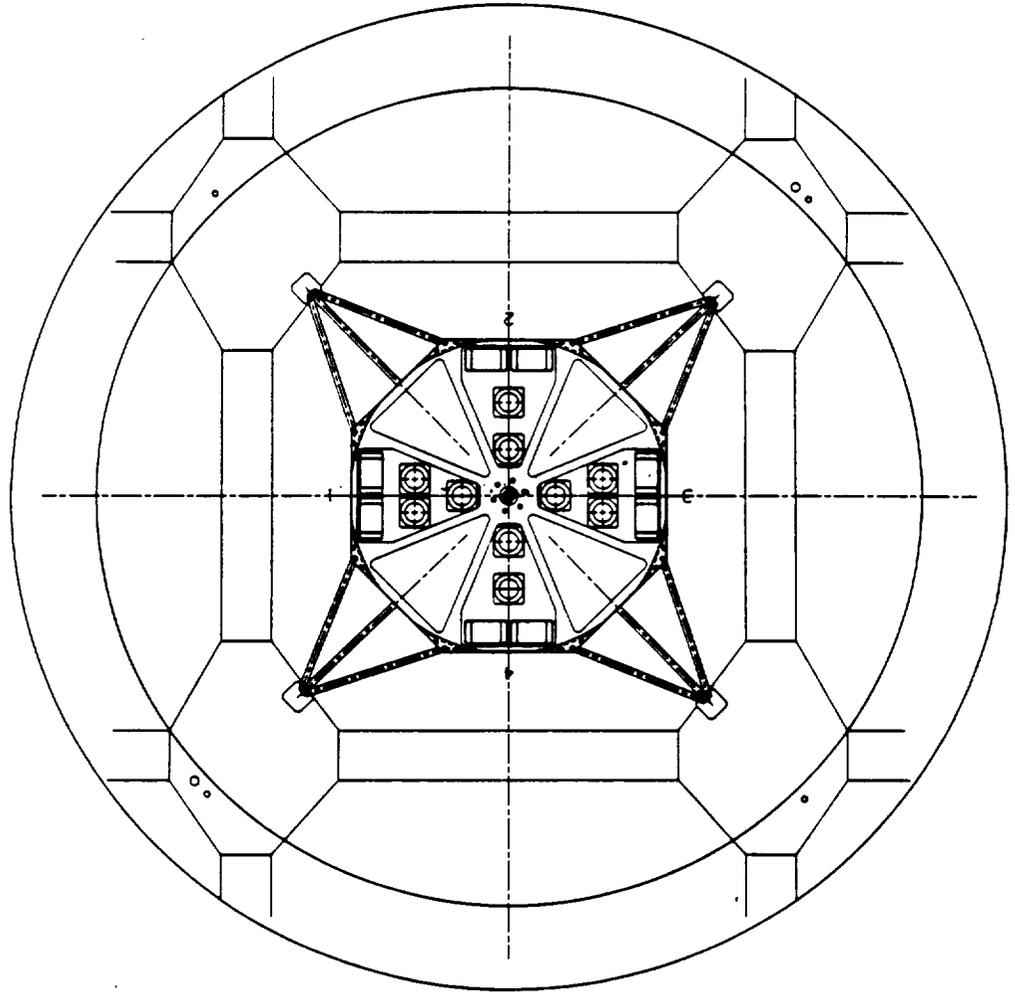
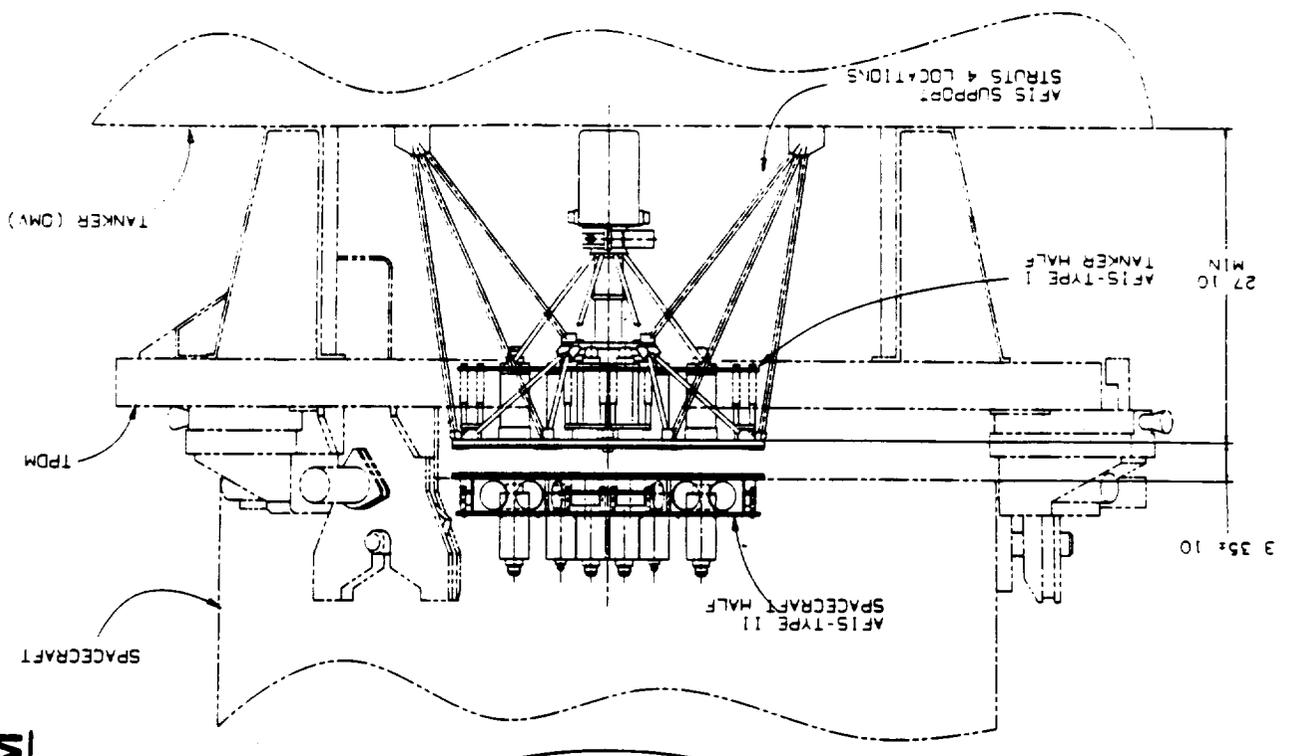
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**AFIS MISALIGNMENT ENVELOPE**

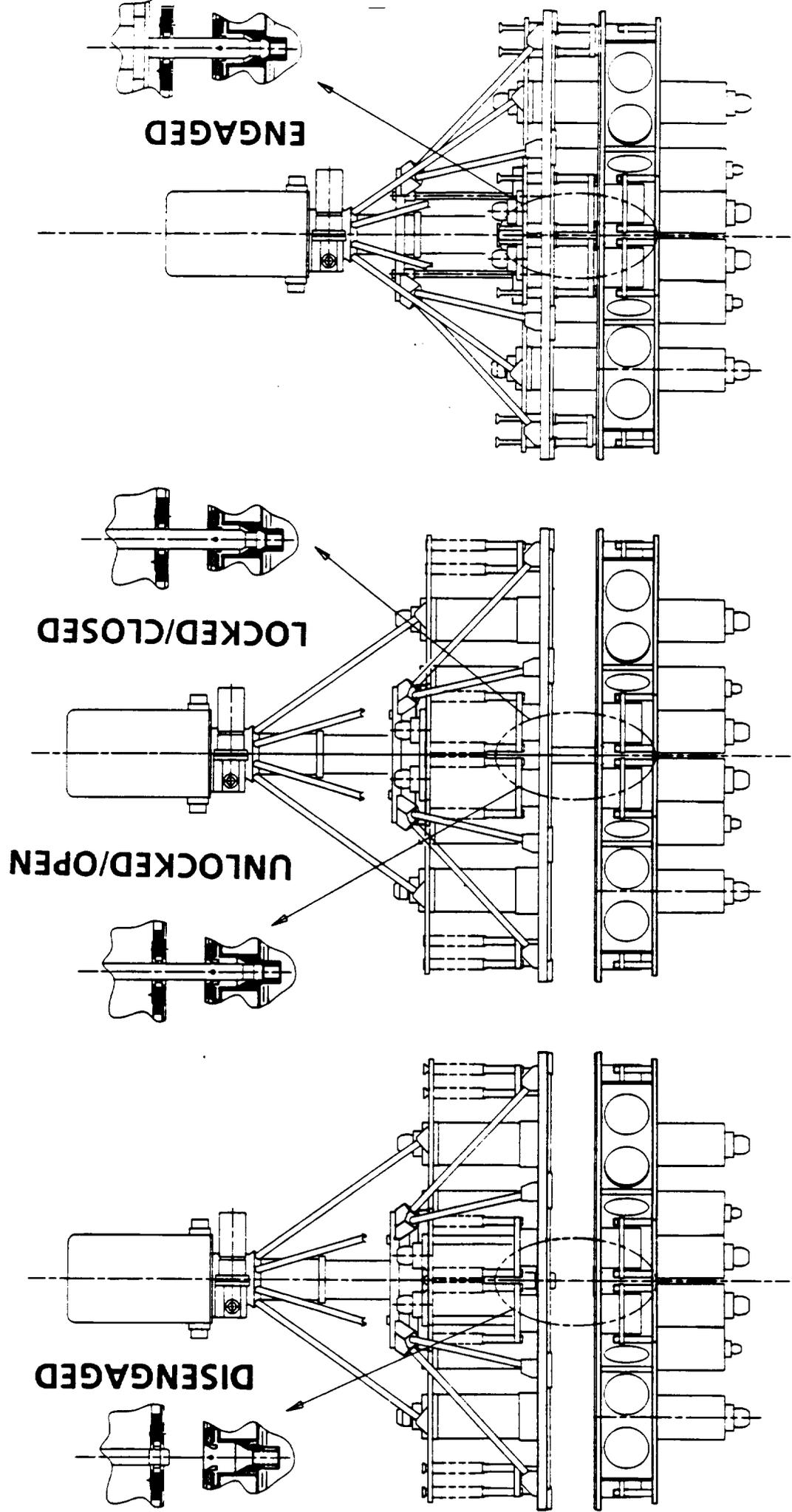


# AFIS WITH TPDM



## AUTOMATED FLUID INTERFACE SYSTEM

# AFIS ENGAGEMENT/DISENGAGEMENT SEQUENCE



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## FUNCTIONAL DESCRIPTION; ENGAGEMENT OF ELECTRICAL CONNECTORS

- ISSUE "ENABLE" AND COMMANDS TO AFIS IN "DISENGAGED" POSITION.
- ACTUATOR ROD BEGINS TO EXTEND RELEASING FLOATING CARRIAGE.
- ACTUATOR ROD TRANSLATES ACROSS INTERFACE TO TAPERED HOLE IN TYPE II COVER.
- CARRIAGE IS PARTIALLY ALIGNED AS ROD ENTERS HOLE IN COVER.
- ACTUATOR ROD CONTINUES TO TAPERED HOLE IN RECEPTACLE.
- ALIGNMENT IS COMPLETE AS ROD ENTERS HOLE IN RECEPTACLE.
- ACTUATOR ROD REACHES FULL EXTENSION THEN ROTATES 45° LOCKING TO RECEPTACLE AND ROTATING COVERS OPEN
- ACTUATOR ROD RETRACTS CAUSING CARRIAGE TO TRANSLATE ACROSS EXPOSED INTERFACE.
- ELECTRICAL CONNECTORS ENGAGE FIRST MAKING ELECTRICAL CONTACT.
- ENGAGEMENT STOPS AT "INITIAL CONTACT" POSITION.
- FLUID COUPLINGS INTERFACED, VALVING ELEMENTS REMAIN CLOSED.
- TANKER MAY NOW INTERROGATE SPACECRAFT TO BE RESUPPLIED.
  - REPROGRAM COMPUTER
  - CHECK SENSORS
  - OPERATE VALVES, HEATERS, ETC.
  - CHARGE BATTERIES

---

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**FUNCTIONAL DESCRIPTION:**  
**ENGAGEMENT OF FLUID COUPLINGS**

- REMOVE THEN REAPPLY "ENABLE" COMMAND TO RESET LOGIC
- ISSUE "ENGAGE" COMMAND TO AFIS IN "INITIAL CONTACT" POSITION
- ACTUATOR ROD RETRACTS CAUSING CARRIAGE TO TRANSLATE TOWARD TYPE II HALF
- FLUID COUPLINGS ENGAGE CAUSING VALVING ELEMENTS TO OPEN
- ELECTRICAL CONNECTORS SIMPLY COMPRESS THEIR MOUNTING SPRINGS
- ENGAGEMENT STOPS AT FULLY "ENGAGED" POSITION
- FLUID RESUPPLY MAY NOW COMMENCE:
  - HIGH PRESSURE GAS
  - WATER
  - MONOPELLANTS
  - BIPELLANTS
  - CRYOGENICS
- AFIS MAY BE POWERED DOWN, WILL HOLD POSITION

**FUNCTIONAL DESCRIPTION:**  
**DISENGAGE OF OXIDIZER COUPLINGS**

- ISSUE "DISENGAGE" COMMAND TO AFIS IN "ENGAGED" POSITION.
- ACTUATOR ROD EXTENDS CAUSING CARRIAGE TO WITHDRAW FROM TYPE II HALF.
- VALVING ELEMENTS CLOSE IN ALL FLUID COUPLINGS.
- OXIDIZER COUPLINGS BREAK INTERFACE SEALS.
- ENGAGEMENT STOPS AT "SPILLAGE VENT" POSITION.
- FUEL COUPLING INTERFACE SEALS REMAIN SEATED.
- ELECTRICAL CONNECTORS REMAIN ENGAGED.
- OXIDIZER SPILLAGE (< 1.0 CC) IS EXPOSED AND QUICKLY DISSIPATES.
- OXIDIZER SEAL INTEGRITY MAY BE VERIFIED.

---

AUTOMATED FLUID INTERFACE SYSTEM

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**FUNCTIONAL DESCRIPTION: DISENGAGEMENT OF AFIS**

- POWER DOWN ALL LINES TO ELECTRICAL CONNECTORS
- REMOVE THEN REAPPLY "ENABLE" COMMAND TO RESET LOGIC
- ACTUATOR ROD EXTENDS CAUSING CARRIAGE TO MOVE AWAY FROM TYPE II HALF
- FUEL COUPLINGS BREAK INTERFACE SEALS EXPOSING FUEL SPILLAGE
- ELECTRICAL CONNECTORS BREAK CONTACTS
- CARRIAGE MOVES TO FULL RETRACTED POSITION CLEAR OF COVER.
- ACTUATOR ROD REACHES FULL EXTENSION THEN ROTATES 45° UNLOCKING FROM RECEPTACLE AND ROTATING BOTH COVERS CLOSED
- ACTUATOR ROD RETRACTS WITHDRAWING FROM THE RECEPTACLE AND TYPE II COVER
- CARRIAGE RELAXES BACK INTO ITS NOMINAL POSITION
- ACTUATOR ROD RETRACTS UNTIL ROD END CATCHES ON TYPE II COVER
- FURTHER RETRACTION CAUSES THE CARRIAGE TO BE SECURELY PRELOADED AGAINST THE TYPE I COVER
- DISENGAGEMENT "STOPS" AT "DISENGAGED" POSITION, AFIS MAY BE POWERED DOWN

---

AUTOMATED FLUID INTERFACE SYSTEM

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## AFIS DESIGN ANALYSIS SUMMARY

- **ACTUATOR DRIVE ANALYSIS**
  - **MOTOR SIZING**
  - **GEAR TRAIN ANALYSIS**
  
- **MECHANICAL STRESS ANALYSIS**
  - **COUPLING SUBPLATES**
  - **ACTUATOR ROD**
  
- **DYNAMIC ANALYSIS**
  - **FINITE ELEMENT MODEL**
  - **RANDOM VIBRATION EXCITATION**
  
- **THERMAL ANALYSIS**
  - **MAX DUTY CYCLE**
  - **LOW TEMPERATURE SOAK**

## AFIS LOADING SUMMARY

- Balanced loads due to engagement of electrical connectors and unpressurized couplings

	QTY	AXIAL LOAD	TOTAL LOAD
Elect. Conn	8	100 lbf.	800 lbf.
Gas Coup	4	20 lbf.	80 lbf.
Equ. Coup.	8	125 lbf.	1000 lbf.
			1880 lbf.

- Unbalanced loads due to holding electrical connectors, unpressurized couplings and one pressurized coupling together.

	QTY.	AXIAL LOAD	TOTAL AXIAL	MOMENT ARM	TOTAL MOMENT
Elect. Conn	8	100 lbf.	800 lbf.	0	0
Gas Coup.	4	20 lbf.	80 lbf.	0	0
Liq. (Unpres)	8	125 lbf.	1000 lbf.	0	0
Liq. (Pres)	1	494 lbf.	495 lbf.	7.0 in.	3898 in.lbf.
			2375 lbf.		3898 in.lbf.

---

AUTOMATED FLUID INTERFACE SYSTEM

# ACTUATOR DESIGN ANALYSIS SUMMARY

Motor Capabilities:		Worm Gear Data: (page 36.10 ref 1)	
Drive Ratio	1 Motor In / Shaft Out	Pitch Diameter	2.5 inches
RPM Input	120 rpm	Number of Teeth	40 #
RPM Output	120 rpm	Face Width of Gear	0.375 inches
Rated Load	5 in/lbs	Gear tangent force, Wgt	75.33 Wgt
Shaft Output	5 in/lbs	Torque Input to ball screw	94.16 in-lbs
<b>Worm Data:</b>		Load Constants:	
Number of Threads	2 #	Ks - Material Factor	800
Lead	0.3927 in/rev	Fe - Effec. Face width	0.375
Lead Angle	11.4 degs	Km - Ratio Correction Fact	0.820
Pressure Angle	14.5 degs	Kv - Velocity Factor	0.637
Pitch Dia of worm	0.625 inches	Estim max load on gear tooth	326.34 lbs
Sliding Vel at worm/gear	20.03 ft/min	Estim Gear Tooth Safety Margin	3.33 Based on Load
Friction, mu	0.01	Worm Gear RPM	6.00 rpm
Tangent worm force, Wx	16.00 lbs	<b>Ball Screw Data:</b>	
Separating Worm Force, Wy	19.91 lbs	Ball Screw Lead	0.5 in/rev
Axial Worm Force, Wz	75.33 lbs	Ball Screw Efficiency	93 %
Efficiency	94.9 %	Aval. Axial Output Force	1100 lbs
Worm RPM	120 rpm	Ball Screw Axial Velocity	3.00 in/min
		Req'd Ball Screw Travel	8.5 inches
		Time For Full Ball Screw Travel	170 seconds

AUTOMATED FLUID INTERFACE SYSTEM

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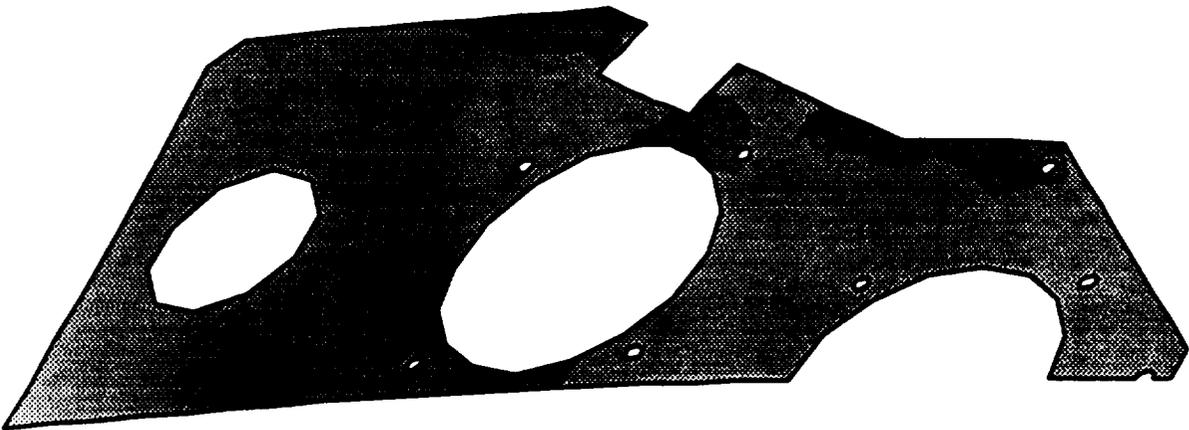
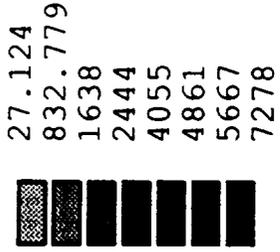
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**COUPLING SUB-PLATE  
STRESS AND DEFLECTION ANALYSIS**

- TYPE I SUBPLATE ANALYZED TO CATILEVERED MOUNTING
- FEA MODEL CREATED AND ANALYZED USING ANSYS 4.4
- STRESS ANALYSIS;
  - 7278 PSI MAX STRESS
  - FACTOR OF SAFETY = 2.7
- DEFLECTION ANALYSIS:
  - 0.075" MAX DISPLACEMENT OF CONNECTOR (ELECTRICAL)
  - WELL WITHIN MISALIGNMENT CAPABILITIES

ANSYS 4.4  
NOV 27 1989  
19:00:06  
PLOT NO. 2  
POST1 STRESS  
STEP=1  
ITER=1  
SIGE (AVG)  
MIDDLE  
DMX =0.126904  
SMN =27.124  
SMX =7278

XV =1  
YV =1  
ZV =1  
DIST=5.896  
XF =2.03  
YF =7.05  
EDGE

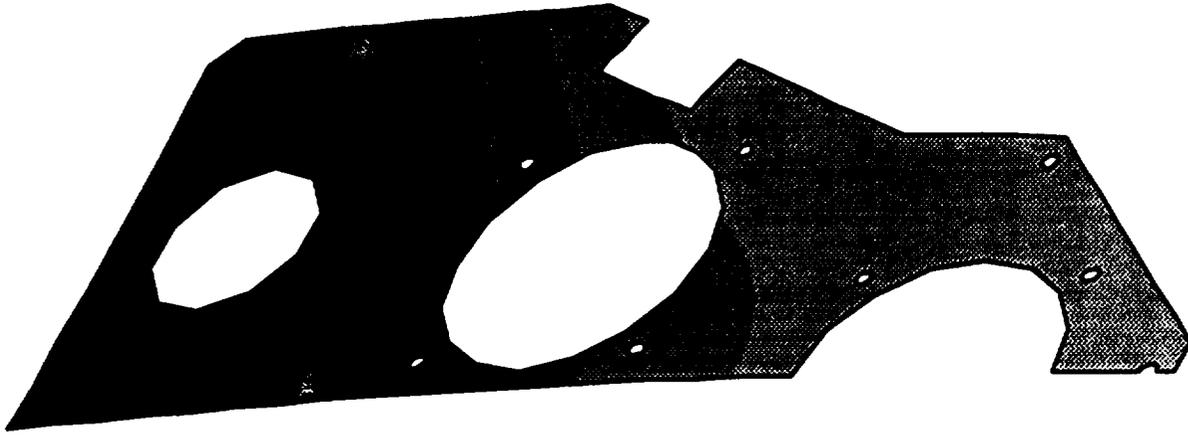


ANSYS 4.4  
NOV 27 1989  
18:58:36  
PLOT NO. 1  
POST1 STRESS  
STEP=1  
ITER=1  
UZ

D GLOBAL  
DMX =0.126904  
SMN =-0.005184  
SMX =0.126904

XV =1  
YV =1  
ZV =1  
DIST=5.896  
XF =2.03  
YF =7.05

EDGE  
-0.005184  
0.009493  
0.024169  
0.038845  
0.068198  
0.082875  
0.097551  
0.126904



# ACTUATOR ROD DESIGN ANALYSIS SUMMARY

Rod Material	
CRES 15-5, Cond 1075	
Yield	125 Ksl
Ultimate	145 Ksl
Modulus	28.5 Msi
Poissons	0.27

Geometry	
Actuator Rod End OD	0.850 in
Actuator Rod End ID	0.500 in
Actuator Rod End Square	0.910 in
Rod Square Thickness	0.5 in

Total Load Applied	#	Load Per	Total Each
<b>Balanced Loads</b>			
Liquid connector	8	125 lbs	1000 lbs
Electrical Connector	8	100 lbs	800 lbs
Gas Connector	4	20 lbs	80 lbs
<b>Unbalanced Load</b>			
Force	495	lbs	495 lbs
Moment Arm, Lx	1.4	in	
Moment Arm, Ly	7.75	in	
Total Axial Load	2375	lbs	
Moment, Mx	3836.3	in-lbs	
Moment, My	683	in-lbs	

Rod Tube Stresses	
Contact distance on rod length of .800 dia	2.4000 in
Moment of Inertia, Square	0.7500 in <sup>4</sup>
Moment of Inertia, round	0.0541 in <sup>4</sup>
Cross-sectional Area	0.0226 in <sup>2</sup>
Round Section	0.3711 in <sup>2</sup>
Axial Stress	6399.9 psi
Bending stress, Sx	22588 psi
Bending stress, Sy	4080.5 psi
Bending Stress, Max	22954 psi
Combined Stress, von Mises	24881 psi
Square Section	
Bending Stress, Max	32800 psi

Stress Concent	Corrected Stress	Factor of Safety	Margin of Safety
4	25599.53	4.882903	3.88290306
2	45176.7	2.766913	1.76691288
2	8160.953	15.31684	14.3168392
2	45907.9	2.722843	1.72284271
2	49761.16	2.511999	1.51199933
1.5	49199.78	2.540662	1.54066178

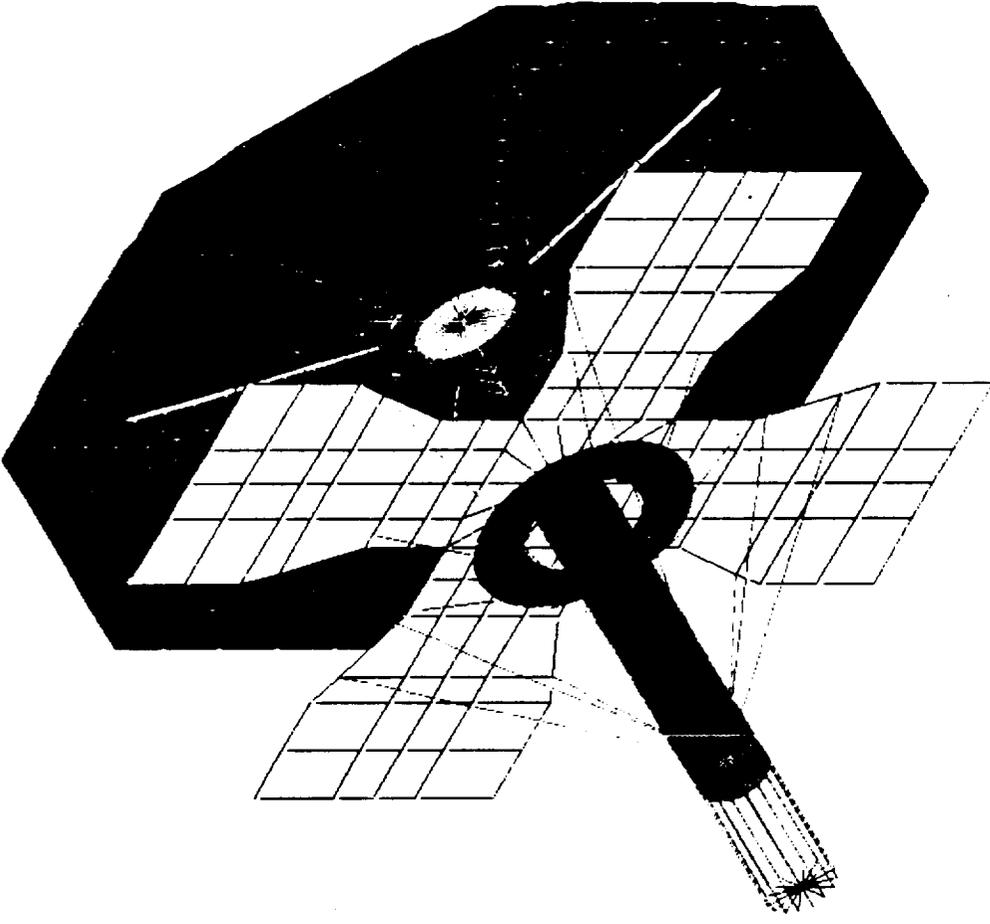
AUTOMATED FLUID INTERFACE SYSTEM

## AFIS

### AFIS Dynamic Analysis

#### Summary

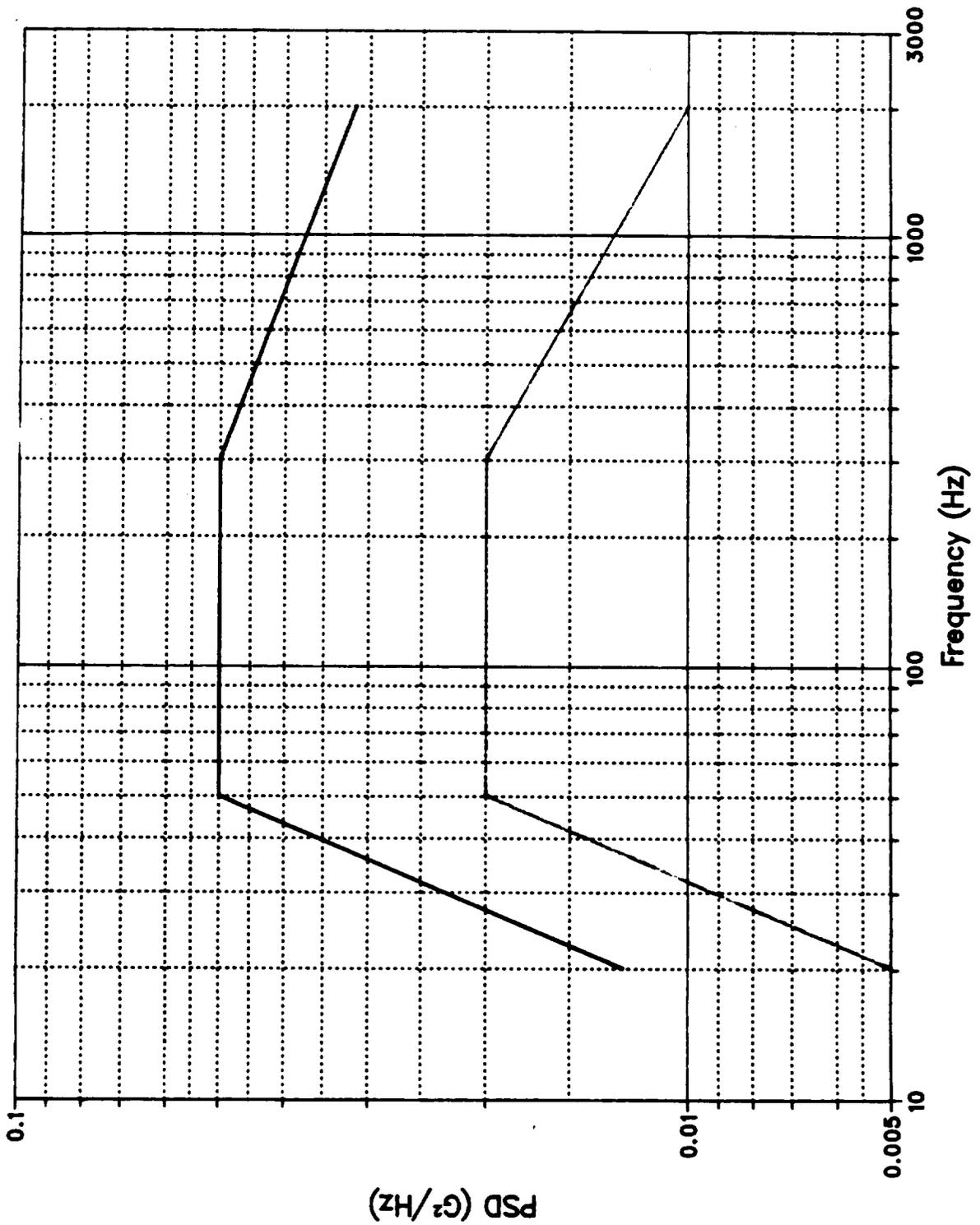
- **The intent of this analysis was to identify severe dynamic weaknesses in the AFIS Type I system**
- **Major component masses and stiffnesses of Type I half included**
- **Mounting plate simply supported at 8 points about perimeter**
- **Harmonic response input at base, 0-3000 Hz, .05 inch input along axis of actuator (Z), and transverse to axis of actuator (X,Y)**
- **The first major resonance in the Z direction was approximately 110 Hz**
- **The first major resonance in the X,Y Directions was approximately 40 Hz**



AFIS FINITE ELEMENT MODEL  
4/19/90  
afis\_a.pic

# RANDOM VIBRATION SPECTRUM

AFIS Actuator and Assy - Qual levels



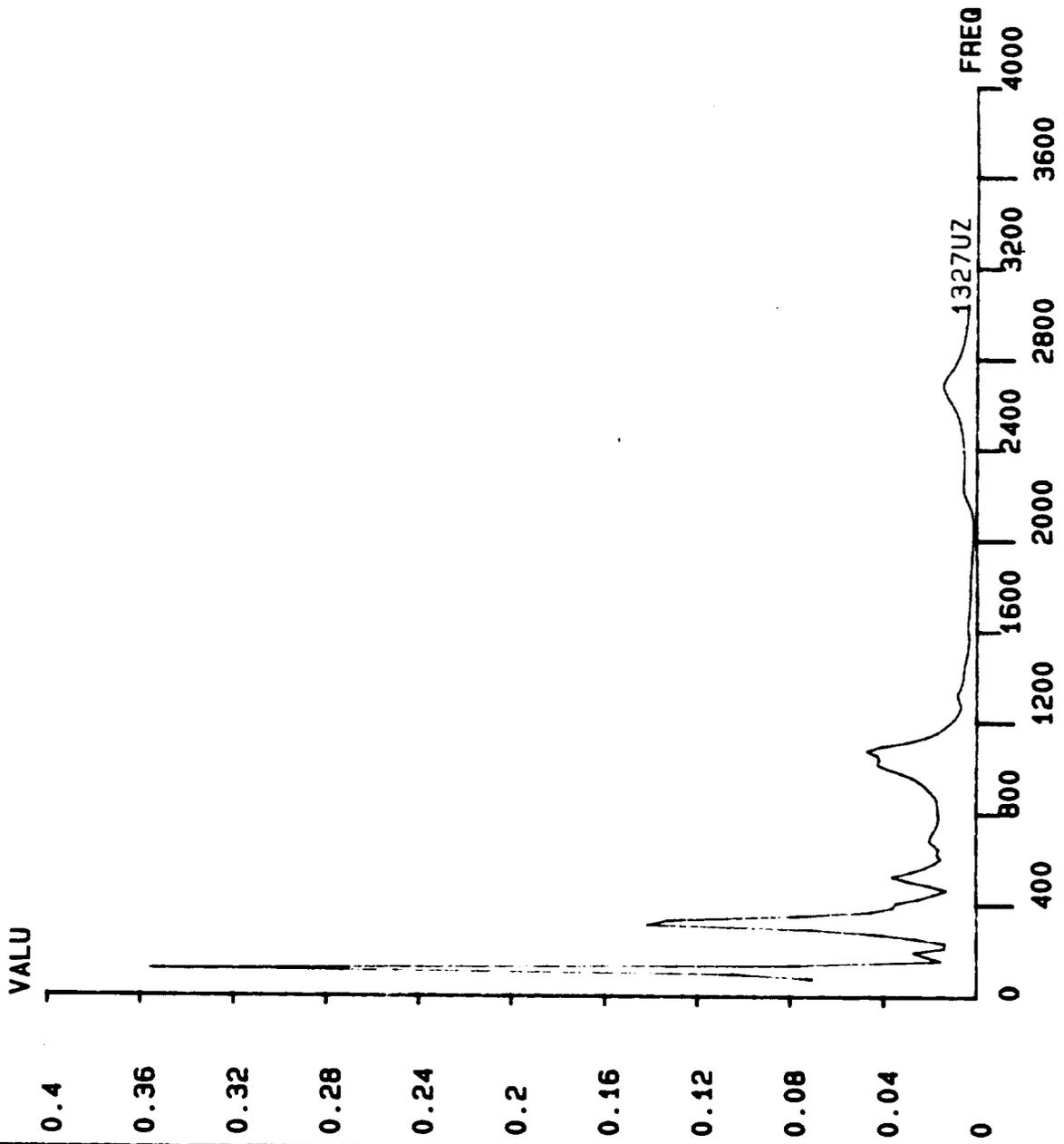
Legend

EQ8 level

EV2 level

ANSYS 4.4  
MAR 21 1990  
09: 47: 04  
PLOT NO. 1  
POST26  
AMPLITUDE

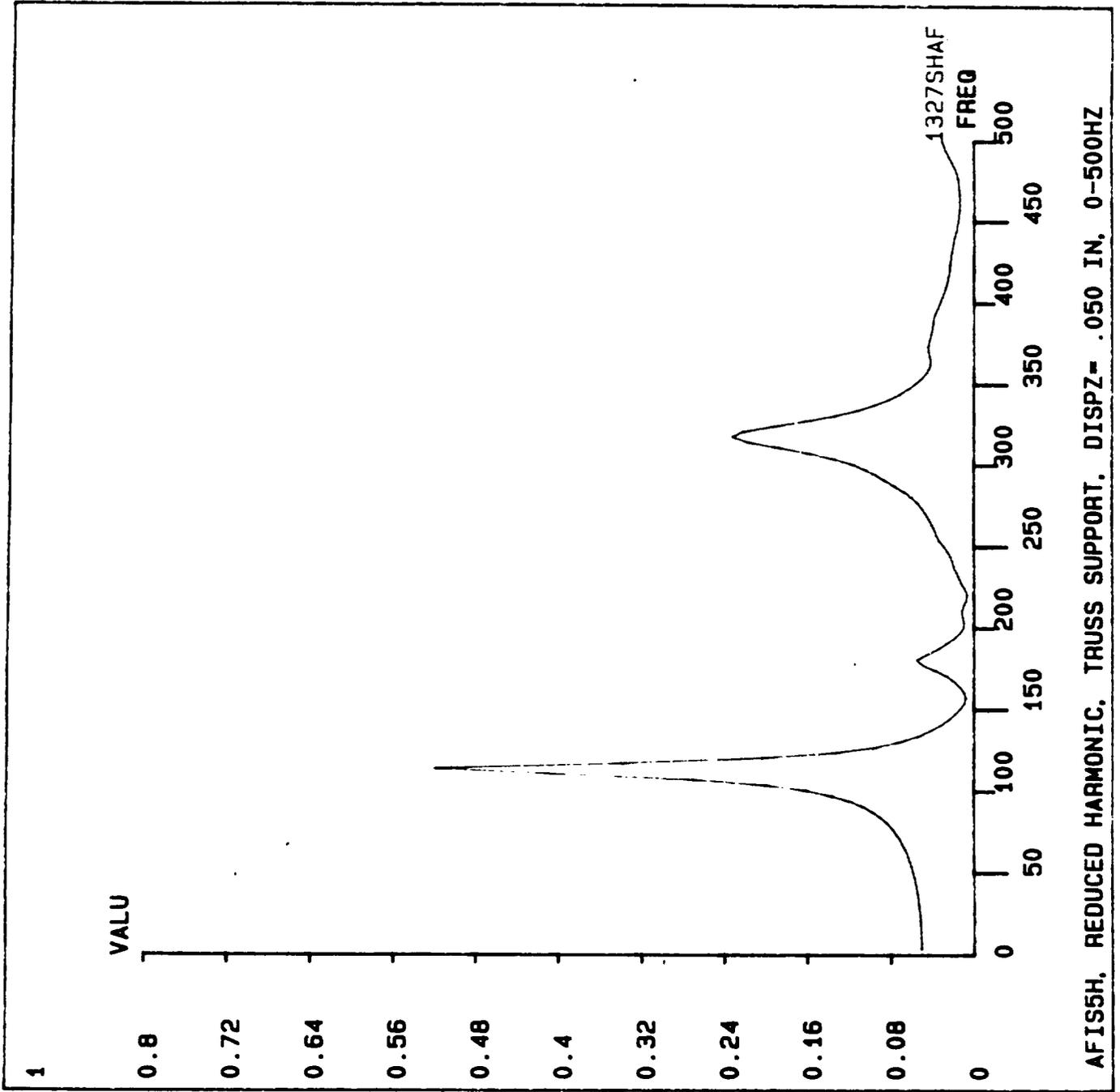
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AFIS5H. REDUCED HARMONIC. TRUSS SUPPORT. DISPZ= .050 IN

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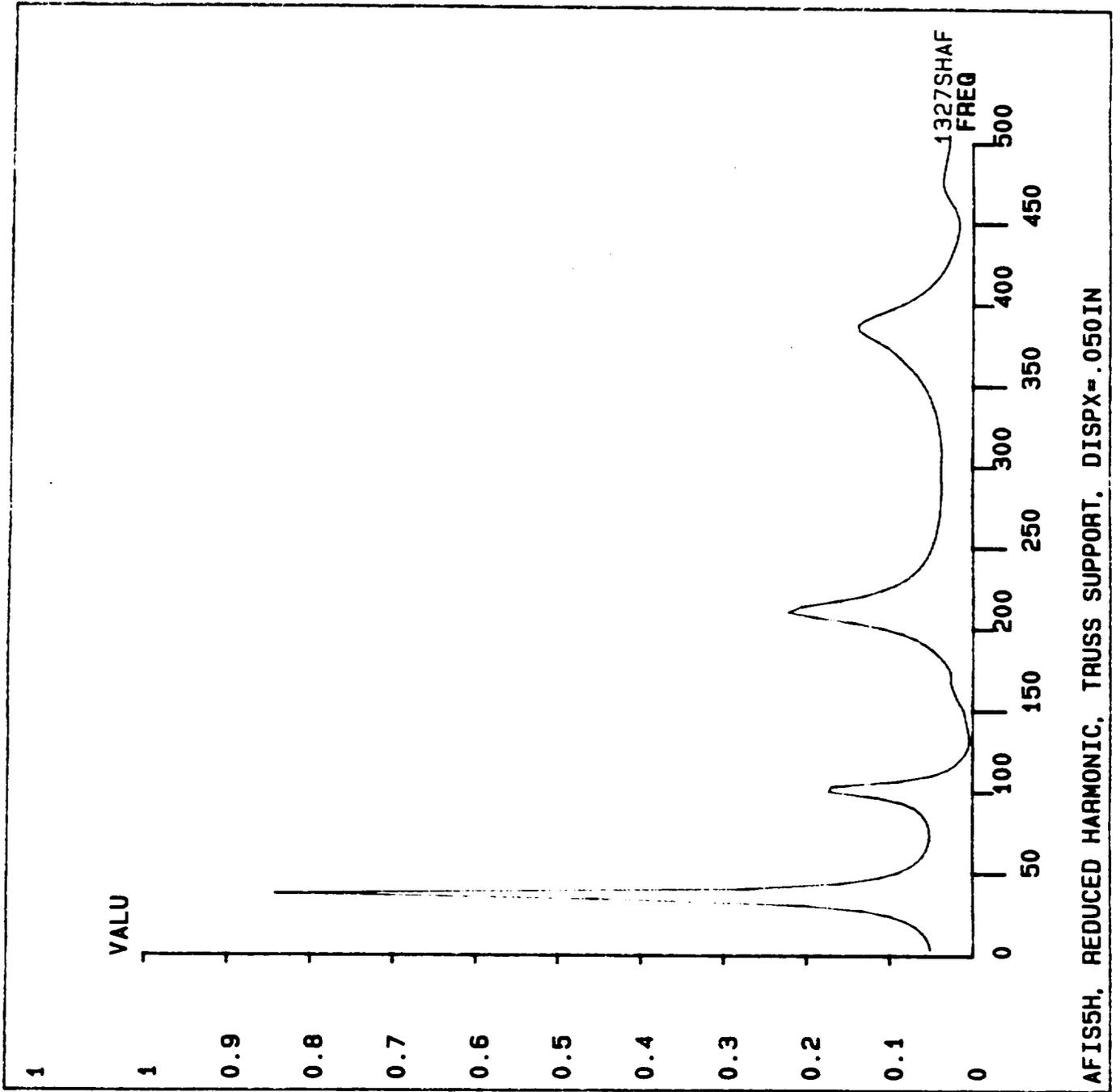
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AFISSH. REDUCED HARMONIC. TRUSS SUPPORT. DISPZ= .050 IN. 0-500HZ

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AMPLITUDE

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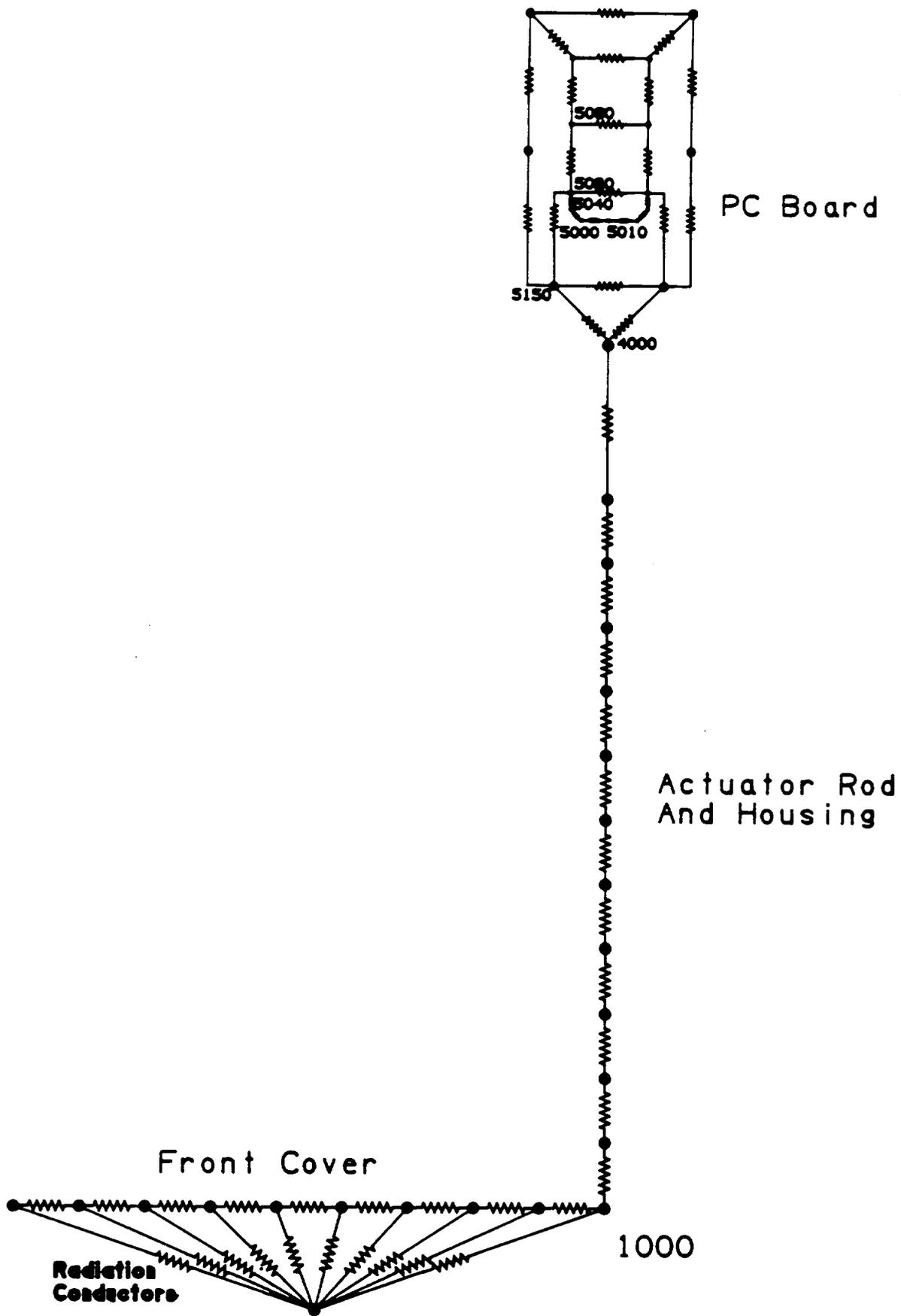


AFIS5H. REDUCED HARMONIC. TRUSS SUPPORT. DISPX=.050IN

### AFIS Thermal Model

#### Approach

- Lumped parameter approach, using TAK-II, of the AFIS Type I half
- Critical thermal paths, masses, and heat sources modelled
- Approximately 40 nodes and 60 linear conductors and radiation links used
- All surfaces assumed insulated against radiation except front cover
- No attachment to craft modelled (thermally isolated except for radiation from cover)
- Primary concern is the temperature of electronics boards and components. Operational temperature range -65 F to 160 F



**AFIS Type 1 Thermal Model**

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## AFIS

### AFIS Thermal Model

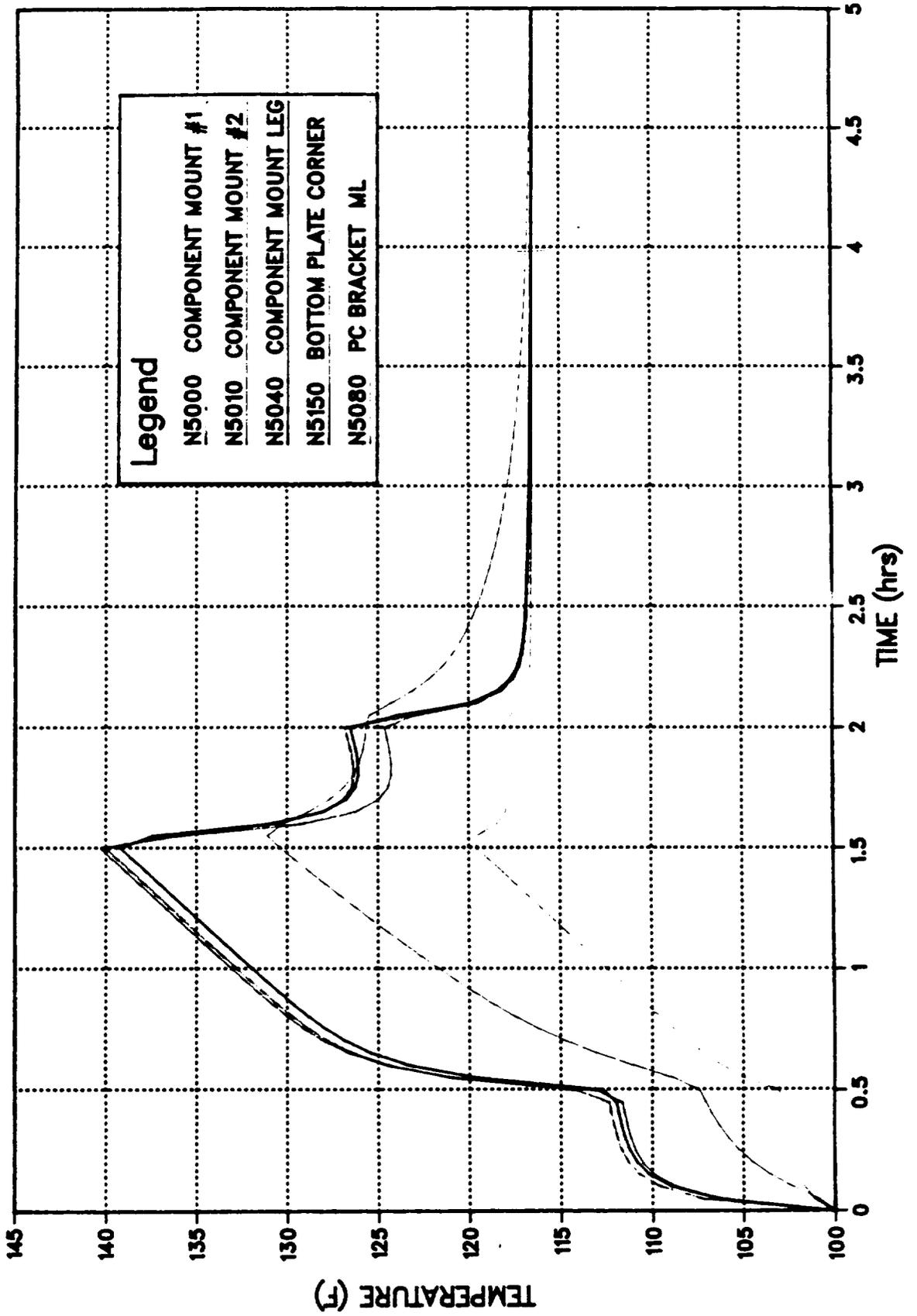
#### Case 1 : Duty Cycle Thermal Analysis

- Duty cycle for Type I half  
(all values in watts)

	Shut Down	Standby	Running
PC Boards	0.0	0.9	0.9
Power Supply	0.0	4.2	10.0
Motor	0.0	0.0	21.0

- Starting temperature for system was 100 F
- No radiation in or out of system
- Maximum temperature of system over cycle was 140 F

### Afis Thermal Analysis Duty Cycle Run - 100 F Start



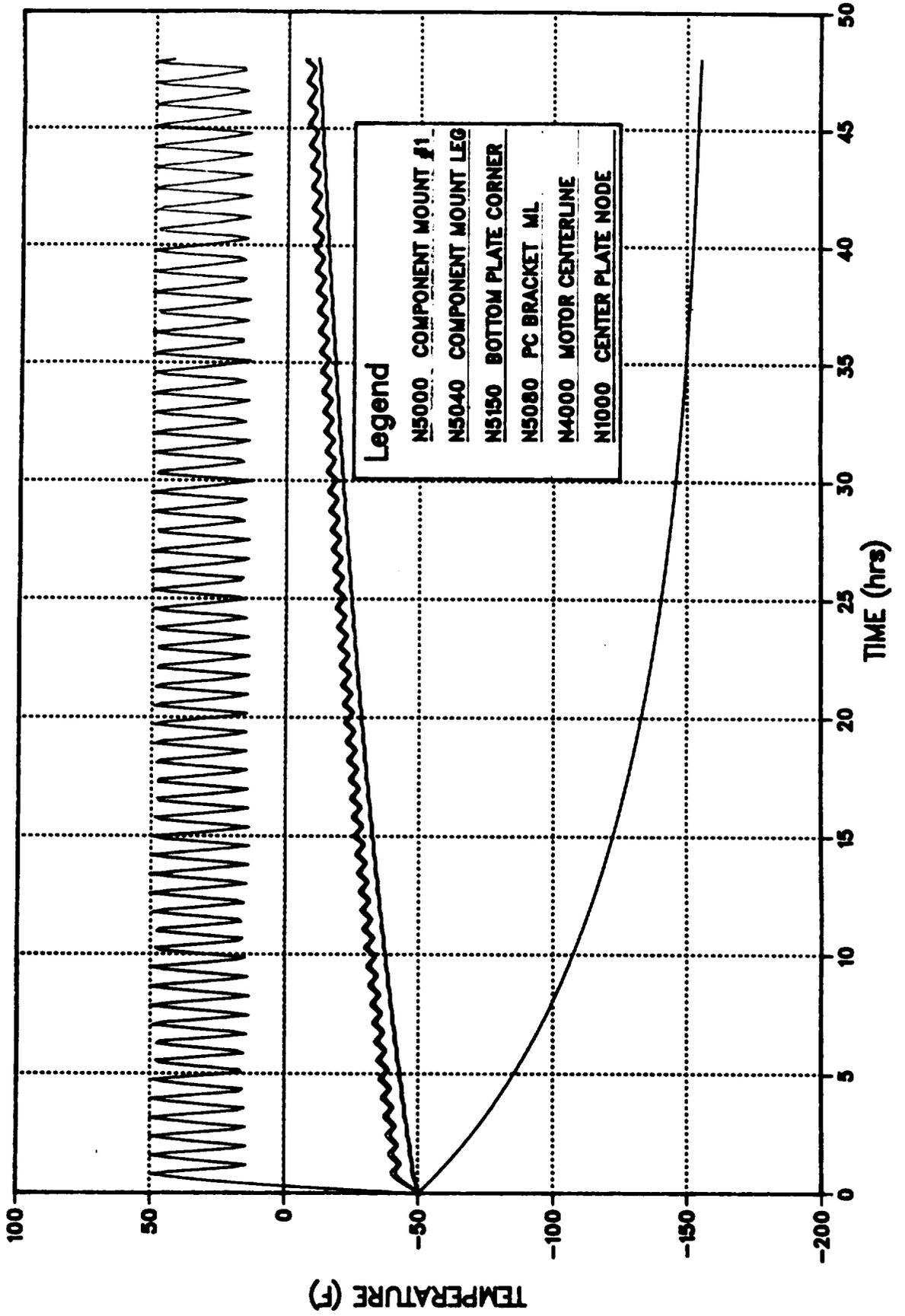
## AFIS

### AFIS Thermal Model

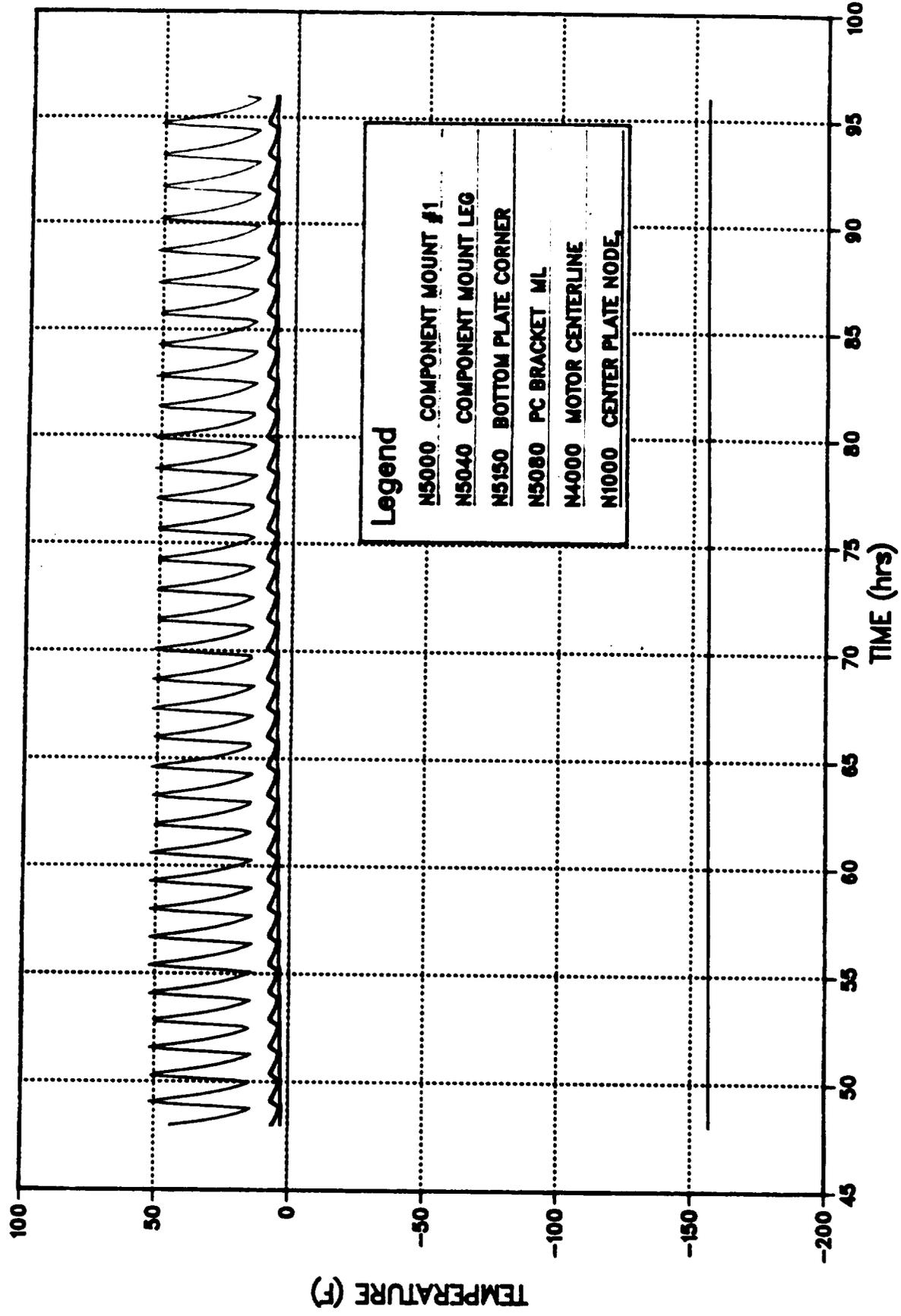
#### Case II : Heater Operation and Sizing

- Steady state analysis with cover maintained at -250 F shows a requirement of less than one watt to maintain PC board at 0 F
- 48 hour transient simulation
- 5 watt thermostatic heater turned on at 14 F, off at 50 F
- Thermostat and heater mounted on PC board bracket approximately 3 inches apart
- -50 F uniform system starting temperature
- Radiation from front cover to -250 F source
- After <sup>96</sup>48 Hours the front cover is tending toward -160 F and the electronics toward the thermostat range.

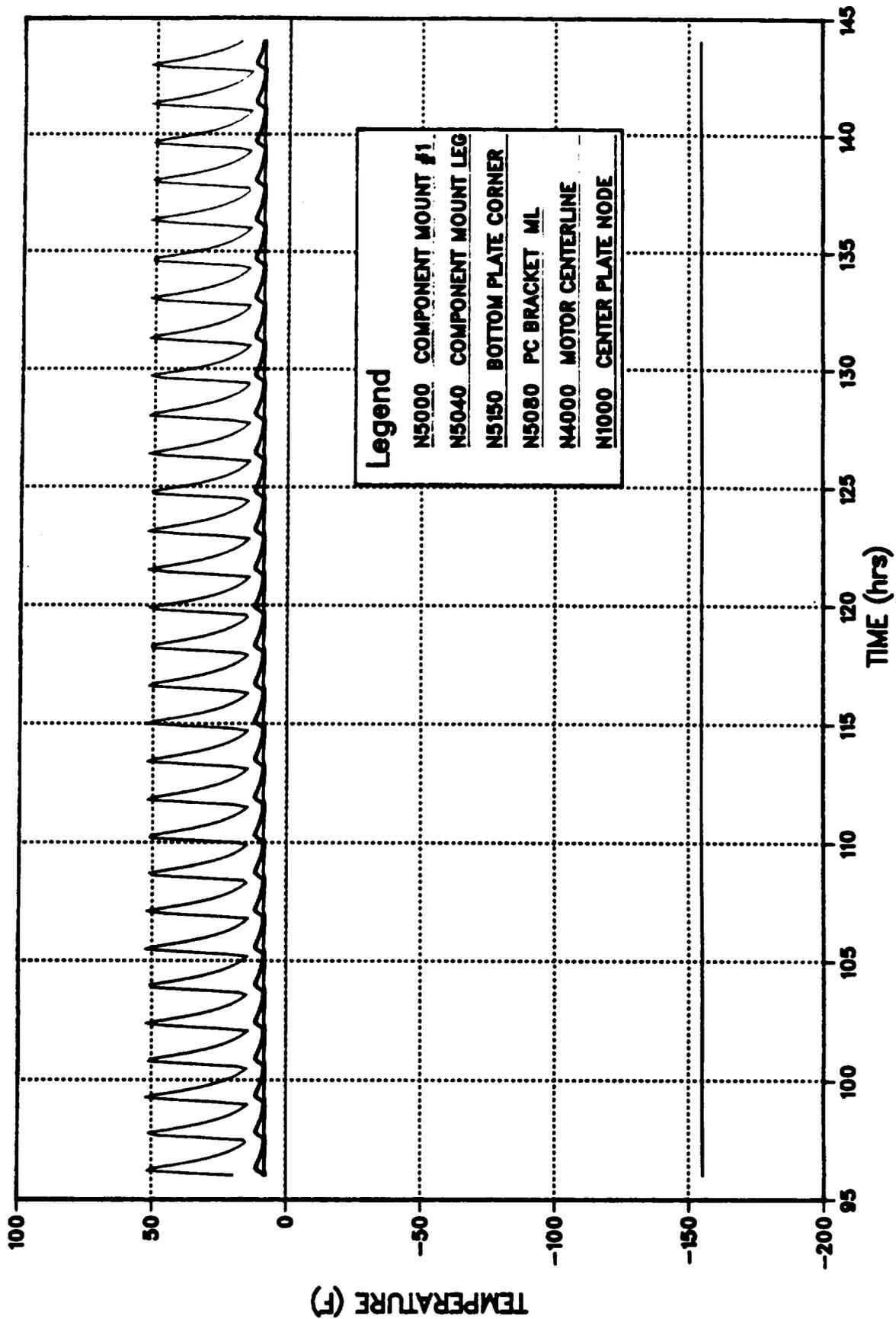
AFIS Thermal Analysis  
Transient heating Run -- -50 F Start



# AFIS Thermal Analysis Transient heating Run - -50 F Start



AFIS Thermal Analysis  
Transient heating Run -- -50 F Start



**DESIGN CHANGES DUE TO ANALYSIS**

- 1) **TRUSS STRUCTURE ADDED TO TYPE I CHASSIS**
- 2) **TYPE I MOUNTING PLATE INCREASED TO 1/2" THICK**
- 3) **TYPE I COVER PLATE INCREASED TO 1/4" THICK**
- 4) **REDUNDANT HEATERS AND THERMOSTATS ADDED**
- 5) **THERMALLY CONDUCTIVE TAPE ADDED TO BOLTED JOINTS**

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## MISSION SUITABILITY FEATURES: USER FRIENDLINESS

- TYPE II HALF IS ESPECIALLY USER FRIENDLY TO ENCOURAGE UTILIZATION AND ACCEPTANCE BY SPACECRAFT MANUFACTURERS:
  - LIGHTWEIGHT TO LIMIT LAUNCH COSTS
  - ELECTRICALLY PASSIVE REQUIRING NO POWER OR DATA
  - MECHANICALLY SIMPLE AND RUGGED FOR MAXIMUM RELIABILITY
  - SMALL ENVELOPE EFFICIENTLY UTILIZES VOLUME
  - COUPLINGS CAN BE "HARDLINED," FLEX HOLES NOT REQUIRED
  - EASILY OPTIMIZED FOR A SPECIFIC SPACECRAFT
- TYPE I HALF SIMPLE TO OPERATE AND RECONFIGURABLE FOR VARIOUS MISSIONS:
  - ELECTRICALLY ACTIVE REQUIRING 28 VDC POWER AND INPUT MISSIONS (15) STATUS SIGNALS ALLOW CONTINUOUS MONITORIN.
  - POWER CAN BE REMOVED AT ANY TIME
    - ACTUATOR WILL STOP AND HOLD POSITION
    - IF POWER REAPPLIED, ACTUATOR WILL REMAIN STOPPED AND WAIT FOR A NEW COMMAND
  - FLUID CONNECTORS REQUIRE APPROX. 3 FT. LONG FLEX HOSES
  - UNOBSTRUCTED FLEX HOSE ROUTING
  - MOVING CARRIAGE "LOCKS DOWN" WHEN IN DISENGAGED POSITION

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AUTOMATED FLUID INTERFACE SYSTEM

## MISSION SUITABILITY FEATURES: RELIABILITY

- EM ACTUATOR BASED ON PROVEN AUC ACTUATOR DESIGN
- POSITION SWITCHES LOCATED INSIDE ACTUATOR, PROTECTED AGAINST DAMAGE OR CONTAMINATION
- SINGLE CENTERLINE ACTUATOR IN LIEU OF MULTIPLE UNITS AROUND PERIPHERY.
- SINGLE MOTOR ALIGNS HALVES, OPERATES COVERS AND ENGAGES/DISENGAGES AFIS
- CAPABLE OF CARRYING COMPLETE SET OF REDUNDANT COUPLINGS.

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## MISSION SUITABILITY FEATURES: SAFETY

- MEETS REQUIREMENTS OF NHB1700.7B, "SHUTTLE PAYLOAD BAY SAFETY REQUIREMENTS."
- POTENTIAL CATASTROPHIC HAZARD POSED BY BIPROPELLANT MIXING
  - PRIMARY PREVENTED BY DESIGN OF COUPLINGS
  - BIPROPELLANT COUPLING PHYSICALLY SEPARATED
  - AFIS STOPS TO ALLOW OXIDIZER SPILLAGE TO DISSIPATE BEFORE FUEL COUPLING IS EXPOSED.
- POTENTIAL CATASTROPHIC HAZARD POSED BY INABILITY TO DISENGAGE
  - ELECTRICAL SYSTEM IS ONE FAILURE TOLERANT
  - EACH CHANNEL HAS A DRIVE HEX FOR MANUAL DISENGAGEMENT
  - APPROACH PATTERNED AFTER DOCKING MECHANISMS
- POTENTIAL CATASTROPHIC HAZARD POSED BY AFIS COMING LOOSE DURING LAUNCH/RE-ENTRY
  - BOTH HALVES MOUNTED BY EIGHT #10 CAPSCREWS
  - ANY FOUR CAPSCREWS WILL SAFETY SECURE AFIS IN PLACE

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AUTOMATED FLUID INTERFACE SYSTEM

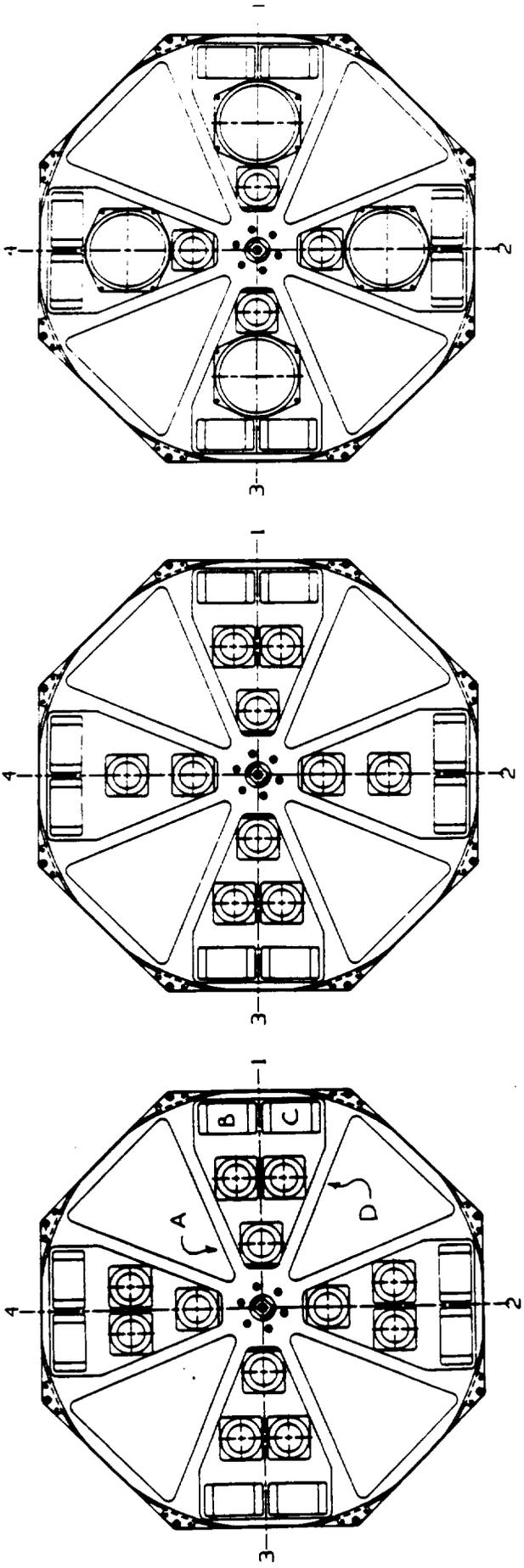
**MISSION SUITABILITY FEATURES: EMERGENCY SEPARATION**

- **INTEGRAL MOTORS USED TO SEPARATE COUPLINGS AND SEVER STRUCTURAL LINK BETWEEN TANKER AND SPACECRAFT**
  
- **24 SEC REQUIRED TO CLOSE ALL COUPLINGS**
  
- **110 SEC REQUIRED TO UNLOCK TYPE I AND II HALVES**
  - **DOCKING MECHANISM CAN NOW UNDOCK**
  - **AFIS HALVES WILL SLIDE APART**
  
- **THIS APPROACH IS FULLY REVERSIBLE**
  
- **OTHER EMERGENCY SEPARATION TECHNIQUES POSSIBLE IF SHORTER TIME IS REQUIRED:**
  - **PYROTECHNIC DEVICES**
  - **SPRING LOADED, ELECTRICALLY ACTIVATED DEVICES**

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**AUTOMATED FLUID INTERFACE SYSTEM**

# MISSION SUITABILITY FEATURES: RECONFIGURABILITY



Group	Site	MONOPROPELLANT CONFIGURATION		MONOPROPELLANT CONFIGURATION		CRYOGENIC CONFIGURATION	
		Connector Type	Connector Function	Connector Type	Connector Function	Connector Type	Connector Function
1	a	Gas	Primary Helium Transfer	Gas	Primary Helium Transfer	Gas	Primary Helium Transfer
	b	Electrical	Primary Avionics	Electrical	Primary Avionics	Electrical	Primary Avionics
	c	Electrical	Primary Avionics	Electrical	Primary Avionics	Electrical	Primary Avionics
	d	Liquid	Primary Fuel Transfer	Liquid	Primary Fuel Transfer	Cryogenic	Primary LH <sub>2</sub> Transfer
2	a	Gas	Primary Nitrogen Transfer	Gas	Primary Nitrogen Transfer	Gas	Primary Nitrogen Transfer
	b	Electrical	Primary Power	Electrical	Primary Power	Electrical	Primary Power
	c	Electrical	Primary Fuel Transfer	Electrical	Primary Fuel Transfer	Electrical	Primary Power
	d	Liquid	Redundant Fuel Usage	Liquid	Redundant Fuel Usage	Cryogenic	Redundant LH <sub>2</sub> Transfer
3	a	Gas	Redundant Helium Transfer	Gas	Redundant Helium Transfer	Gas	Redundant Helium Transfer
	b	Electrical	Redundant Avionics	Electrical	Redundant Avionics	Electrical	Redundant Avionics
	c	Electrical	Redundant Avionics	Electrical	Redundant Avionics	Electrical	Redundant Avionics
	d	Liquid	Primary Oxidizer Transfer	Liquid	Primary Oxidizer Transfer	Cryogenic	Primary LO <sub>2</sub> Transfer
4	a	Gas	Redundant Nitrogen Transfer	Gas	Redundant Nitrogen Transfer	Gas	Redundant Nitrogen Transfer
	b	Electrical	Redundant Power	Electrical	Redundant Power	Electrical	Redundant Power
	c	Electrical	Redundant Power	Electrical	Redundant Power	Electrical	Redundant Power
	d	Liquid	Redundant Oxidizer Transfer	Liquid	Redundant Oxidizer Transfer	Cryogenic	Redundant LO <sub>2</sub> Transfer

## AUTOMATED FLUID INTERFACE SYSTEM

**MISSION SUITABILITY FEATURES:**  
**COUPLING/CONNECTOR ACCOMODATION**

- **AFIS CAPABLE OF CARRING (12) FLUID AND (8) ELECTRICAL CONNECTORS OR (4) FLUID, (4) CRYOGENIC AND (8) ELECTRICAL CONNECTORS**
- **ACCOMMODATES BOTH FAIRCHILD AND MOOG FLUID COUPLINGS**
- **COVERS PROTECT SENSITIVE COUPLING INTERFACES**
- **FLUID COUPLINGS THERMALLY ISOLATED FROM AFIS**
- **COUPLINGS/CONNECTORS MOUNTED TO REMOVABLE SUB-PLATES**
  - **QUICK, SIMPLE, GANGED CHANGE-OUT**
  - **CUSTOM SUBPLATES CAN ACCOMODATE FUTURE REQUIREMENTS**
- **PROVIDES 2650 LBF OF FORCE TO ENGAGE AND LATCH COUPLINGS**
- **LONG (1.4 INCH) STROKE AVAILABLE TO OPERATE COUPLINGS**
- **AUTOMATICALLY ALIGNS COUPLINGS TO WITHIN THEIR MISALIGNMENT ENVELOPE**

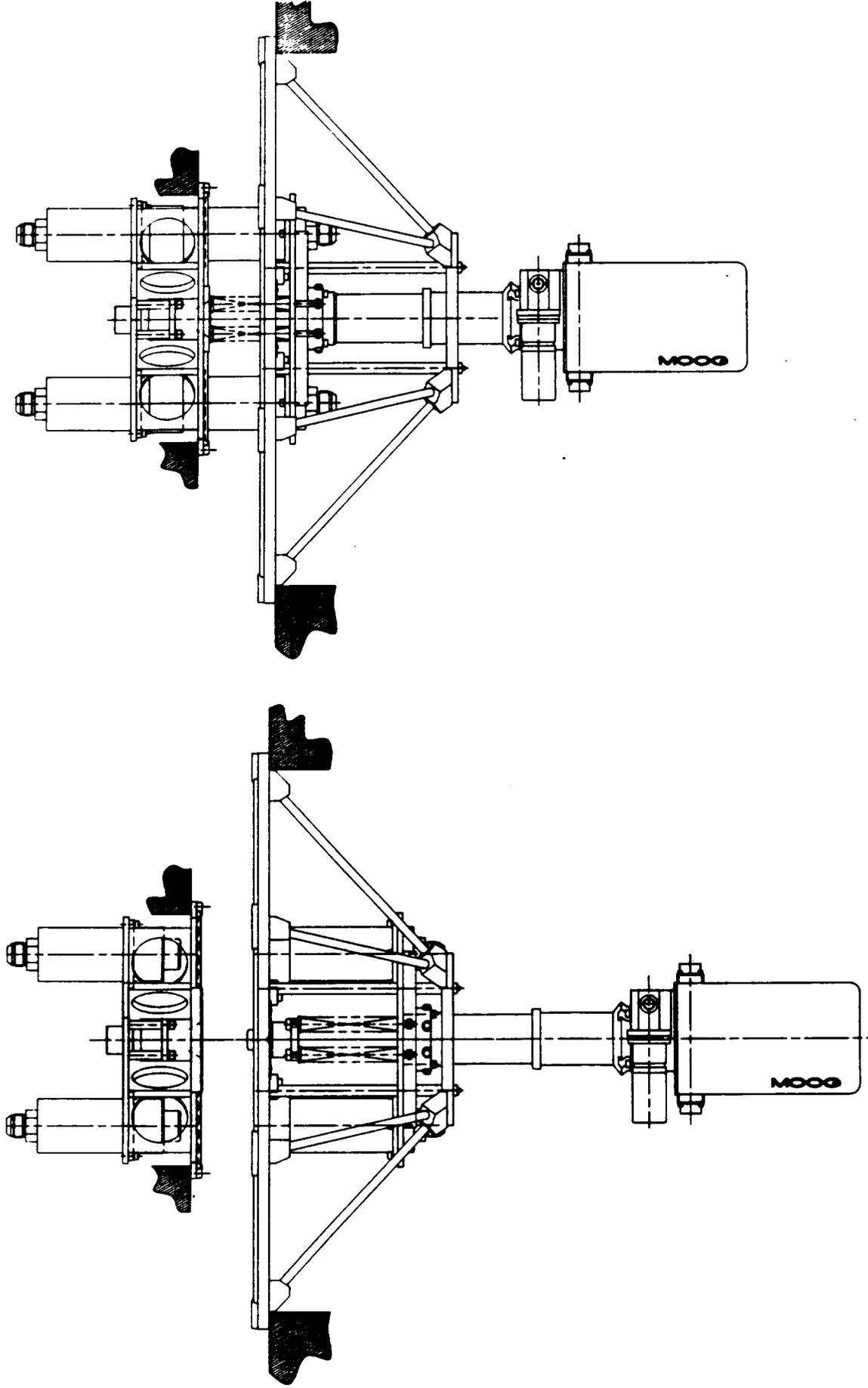
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**MISSION SUITABILITY FEATURES: FLEXIBILITY**



- FULL SIZE TANKER HALF COMPATIBLE WITH DOWNSIZED SPACECRAFT HALF

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## **MISSION SUITABILITY FEATURES: DOCKING MECHANISM COMPATIBILITY**

- **COMPATIBLE WITH ALL KNOWN DOCKING MECHANISMS**
- **AFIS COMPATIBLE AS IS, ONLY MOUNTING STRUCTURE CHANGES**
- **COUPLING LOADS BORNE BY AFIS, TRANSMITTED FORCE LESS THAN 20 LBF.**
- **WIDE RANGE OF PLACEMENT OPTIONS**
- **ACCOMMODATES MAX POTENTIAL MISALIGNMENT AFTER DOCKING**

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## **MISSION SUITABILITY FEATURES: COST CONTROL**

- **THE DESIRE TO CONDUCT ON-ORBIT RESUPPLY IS ECONOMICALLY BASED.**
- **SIMPLE, STRAIGHTFORWARD DESIGN MINIMIZES MANUFACTURING COSTS.**
- **LIGHTWEIGHT DESIGN LOWERS LAUNCH COSTS.**
- **BASED ON SUCCESSFUL EXISTING DESIGN TO MINIMIZE SCHEDULE AND COST RISK.**
- **BUILT-IN ELECTRONICS SIMPLIFIES INTEGRATION COMPARED TO DESIGNS WITH A SEPARATE "BLACK BOX."**

TESTING: MOOG AFIS TEST DATA SUMMARY

- **ACTUATOR TESTING:**

	<u>RUNNING</u>	<u>PEAK</u>
- <b>MANUAL OPERATION</b>	5 IN-LB.	7 IN-LB.
- <b>STALL TORQUE:</b>	45 IN-LB.	45 IN-LB.
  
- **AFIS SYSTEM FUNCTIONAL DEMONSTRATION TESTING:**
  - **CONFIGURE FOR BIROPELLANT RESUPPLY**
  - **10 ENGAGE/DISENGAGE CYCLES, FULL COMPOUND MISALIGNMENT**
  - **INSPECT FOR WEAR OR DAMAGE**
  - **REPEAT WITH AFIS CONFIGURED FOR MONOPROPELLANT & CRYOGENIC RESUPPLY**
  
- **RESULTS:**

-- <b>MANUAL OPERATION</b>	15 IN-LB.	25 IN-LB.
-- <b>FORCE MARGIN</b>	200%	80%
-- <b>POWER DRAW</b>	28 WATTS	56 WATTS
-- <b>TIME REQUIRED TO ENGAGE</b>	3:42 (MINUTES:SEC)	
-- <b>TIME REQUIRED TO DISENGAGE</b>	3:36 (MINUTES:SEC)	

AUTOMATED FLUID INTERFACE SYSTEM

**SUGGESTED NASA TESTING**

- REPEAT AFIS FUNCTIONAL TESTING PERFORMED BY MOOG
- FLAT FLOOR RESUPPLY DEMONSTRATION
  - CONFIGURE AFIS WITH TWO FUNCTIONAL FLUID COUPLINGS
  - MOUNT TYPE I HALF ON TANKER MOCK-UP
  - MOUNT TYPE II HALF ON SPACECRAFT MOCK-UP
  - FLY TANKER TO SPACECRAFT, DOCK AND ENGAGE AFIS
  - TRANSFER FLUID FROM TANKER TO SPACECRAFT
  - DISENGAGE AFIS, UNDOCK, FLYOFF
- THERMAL VACUUM TESTING
- MEASURE DOCKING SYSTEM LOADING
- RANDOM VIBRATION TESTING
- POTENTIAL UTILIZATION OF AFIS FOR NRA PROGRAM
  - THERMAL VACUUM ENVIRONMENT
  - OUTFITTED WITH (2) CRYOGENIC COUPLINGS
  - PERFORM ACTUAL CRYOGEN TRANSFER

**CONCLUSIONS**

- **THE NASA/MOOG AFIS IS IDEALLY SUITED AS AN AUTOMATED FLUID TRANSFER INTERFACE SYSTEM FOR USE WITH FUTURE TANKERS AND SPACECRAFT**
- **THE AFIS IS FULLY COMPLIANT WITH ALL DESIGN REQUIREMENTS**
- **EXTREMELY LIGHTWEIGHT, THE AFIC CARRIES UP TO 2 1/2 TIMES ITS OWN WEIGHT**
- **THE AFIS IS COMPATIBLE WITH ALL DOCKING MECHANISMS INCLUDING SINGLE AND TRIPLE POINT TYPES**
- **THE AFIS IS REUSEABLE FOR GROUND SERVICING AND GROUND LAUNCHED SERVICING TO ALL ORBITS**
- **SIMPLE, STRAIGHT FORWARD DESIGN HAS MINIMIZED LIFE CYCLE COSTS**
- **RELIABILITY HAS BEEN MAXIMIZED THROUGH SIMPLICITY AND REDUNDANCY**
- **THE CENTERLINE MOUNTED ACTUATOR DESIGN IS INHERENTLY FLEXIBLE**
- **MONOP, BIPROP AND CRYOGENIC CONFIGURATIONS HAVE BEEN FUNCTIONALLY DEMONSTRATED**

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**AUTOMATED FLUID INTERFACE SYSTEM**

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**UNIVERSAL RESUPPLY INTERFACE SYSTEM (URIS)**

- **ONE SYSTEM DESIGNED, BUILT AND TESTED UNDER MOOG IR & D**
- **USES AFIS ACTUATOR AND RECEPTACLE**
  - **SAME MISSION SUITABLE FEATURES**
  - **MUCH SMALLER AND LIGHTER**
- **COUPLING CLUSTER SCALED FOR APPLICATION**
  - **TWO TO TWENTY COUPLINGS/CONNECTORS**
- **SMALL URIS IDEAL FOR S3 FLIGHT EXPERIMENT**
  - **SUGGEST TWO PROPELLANT COUPLINGS AND TWO ELECTRICAL CONNECTORS**
  - **LIGHT WEIGHT: 43.9 LBM TOTAL (INCLUDING COUPLINGS)**
  - **TECHNOLOGY RELEVANT TO EVENTUAL TANKER INTERFACE**
- **MEDIUM IRIS IDEAL FOR SSF LOGISTIC SUBCARRIER INTERFACE:**
  - **EIGHT FLUID/ELECTRICAL CONNECTOR SITES**
  - **LIGHT WEIGHT: 70.2 LBM (INCLUDING COUPLINGS)**
  - **COULD BE USED AS DOCKING MECHANISM**

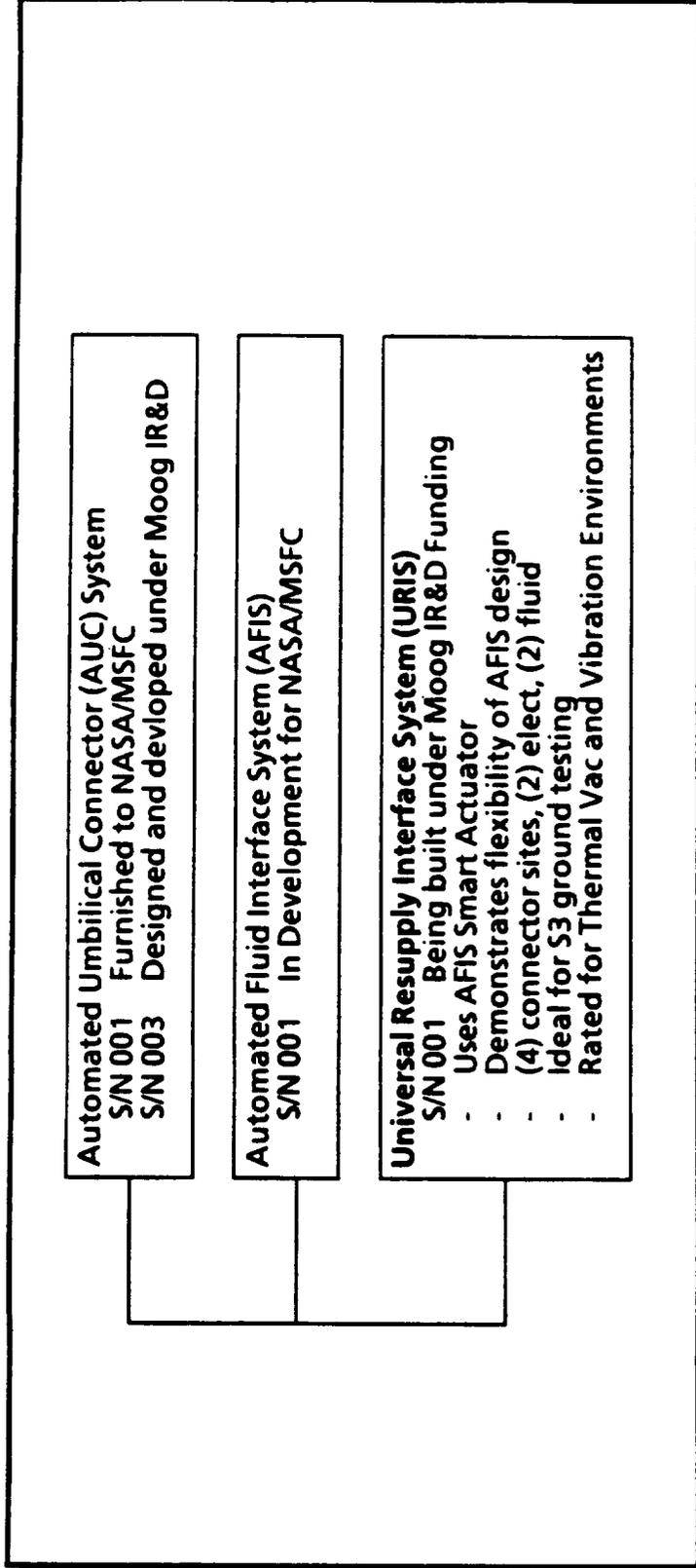
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**AUTOMATED FLUID INTERFACE SYSTEM**

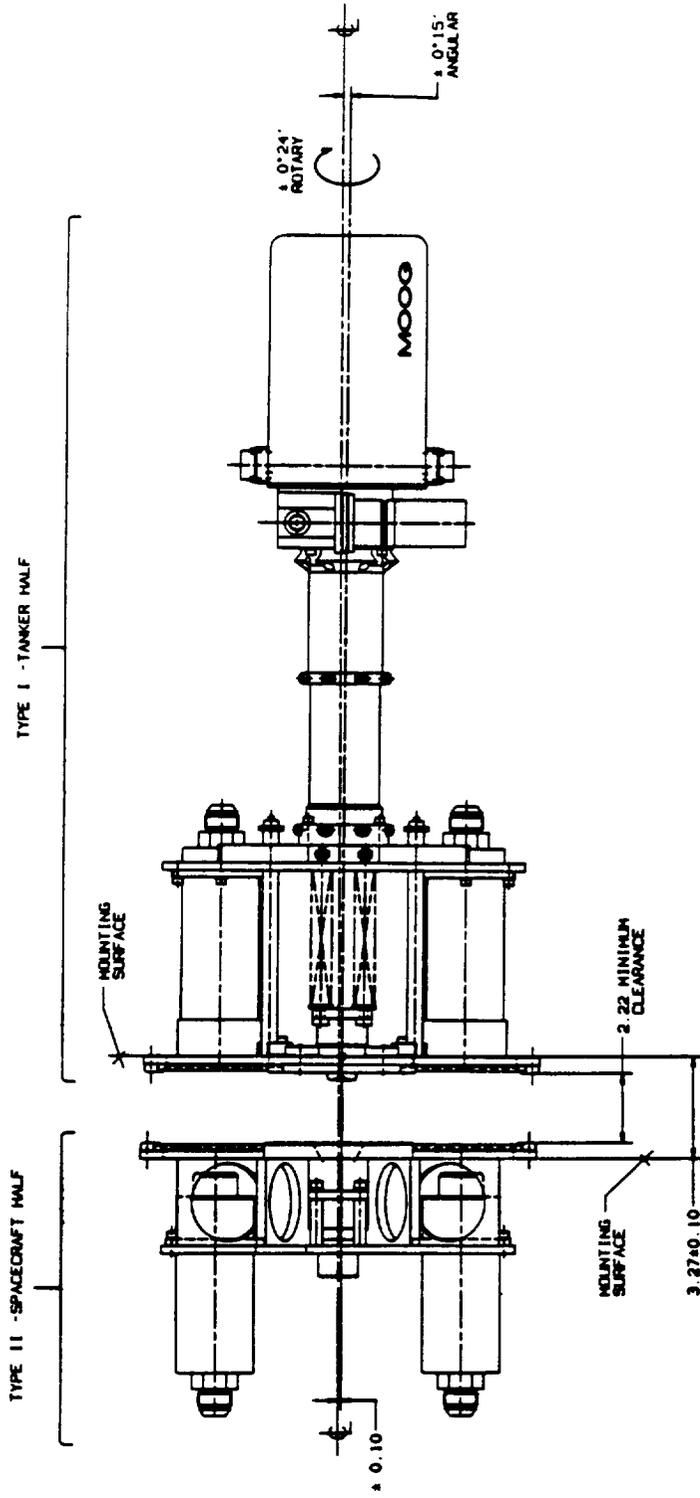
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# RELATED IR&D ACTIVITY: URIS



# SMALL URIS



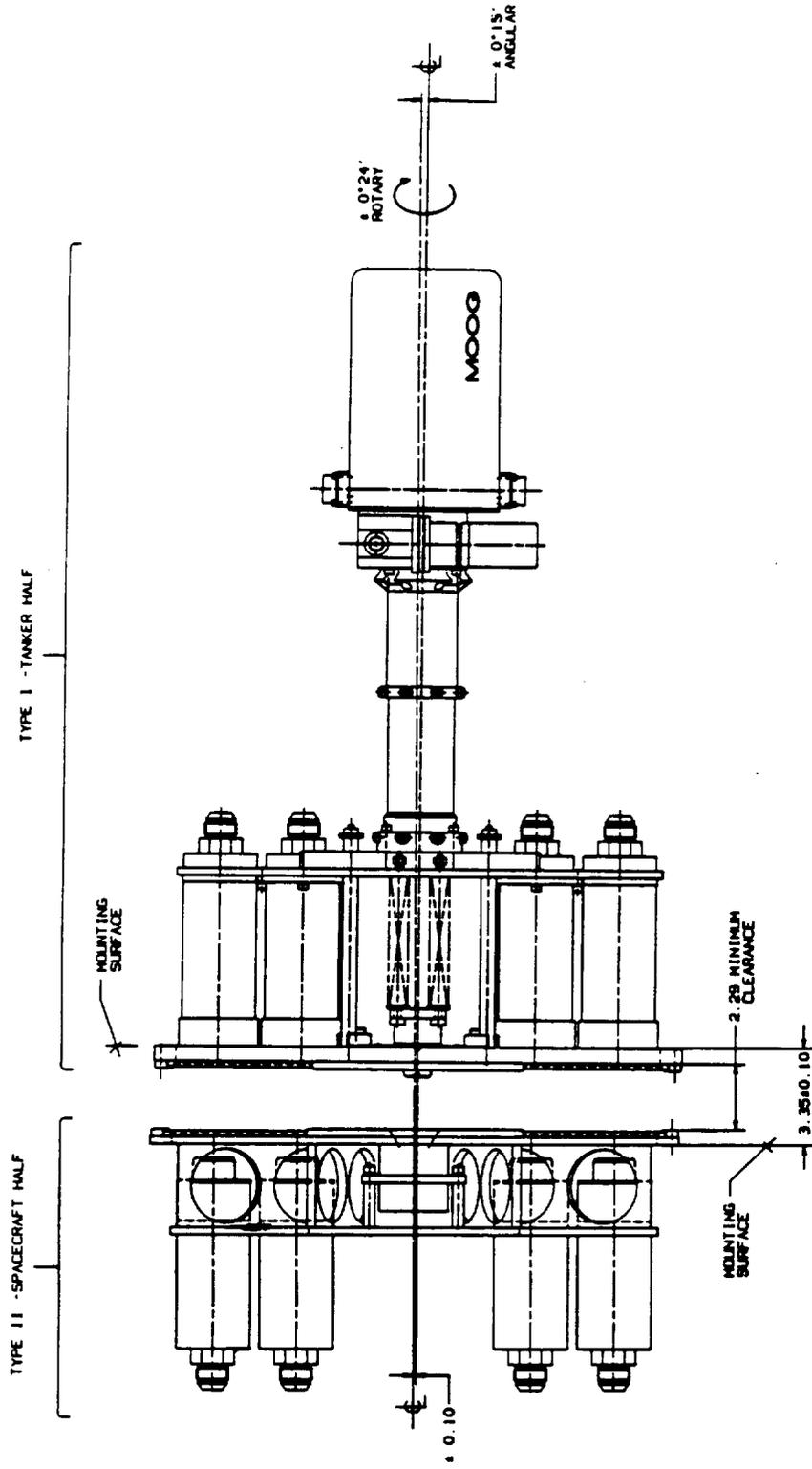
- FOUR CONNECTOR SITES
- IDEAL FOR S<sup>3</sup> FLIGHT EXPERIMENT

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# MEDIUM URIS



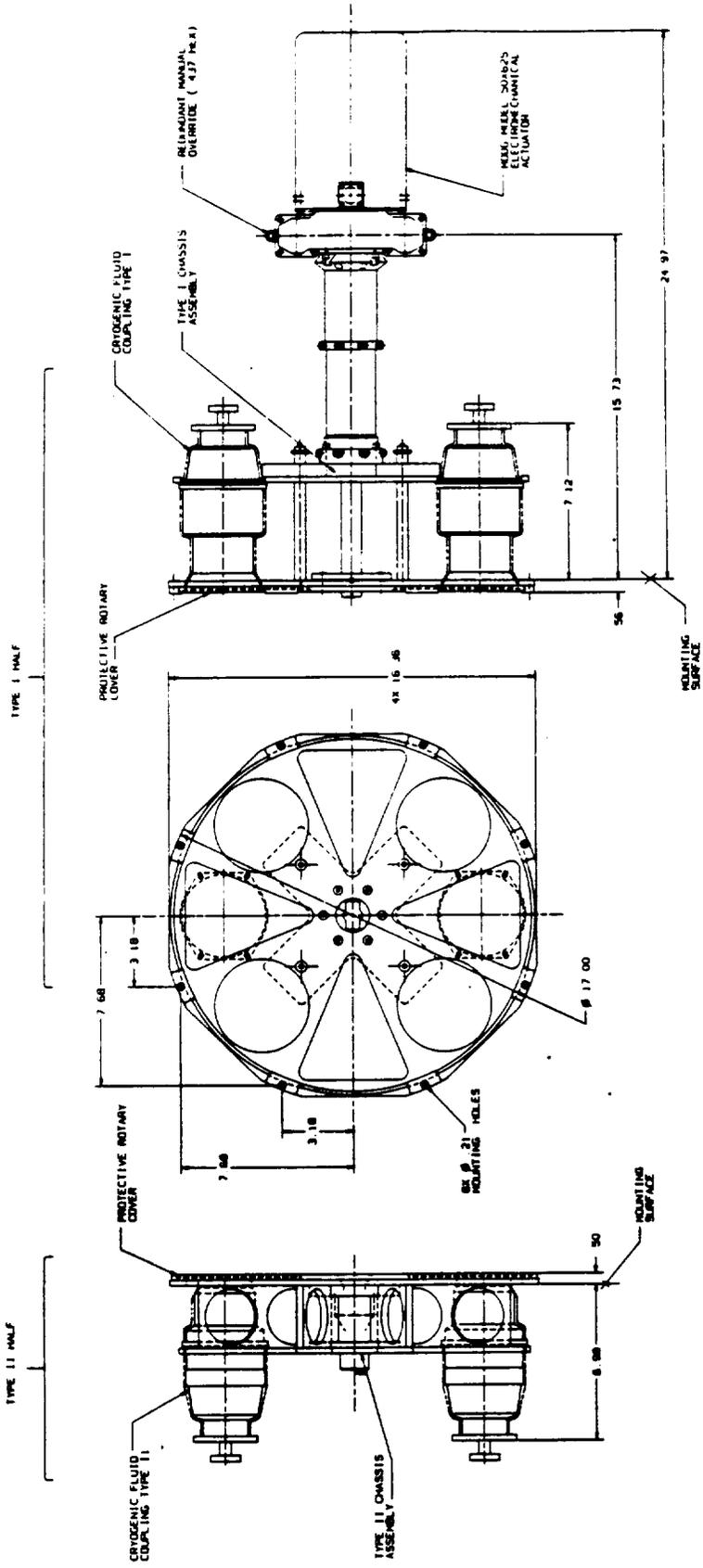
- TEN CONNECTOR SITES
- IDEAL FOR SSF UNPRESSURIZED LOGISTICS MODULE

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# MOOG CRYOGENIC URIS



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PROPOSAL DRAWING

NOTES

- URIS AS SHOWN HAS (6) LARGE CONNECTION SITES AS AN EXAMPLE THE STRAIN IS SOON CONFIRMED WITH THE MOOG CRYOGENIC URIS FOR FUTURE DEVELOPMENT.
- WEIGHT (LBS) URIS COUPLERS TOTAL  
 TYPE I HALF 75.8 : 18.8 : 28.8

## AUTOMATED FLUID INTERFACE SYSTEM

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**TENTATIVELY PLANNED URIS TESTING**

- **MOOG FUNCTIONAL DEMONSTRATION**
- **NASA JSC TRANSFER DEMO:**
  - **URIS CONFIGURED WITH (1) HYDRAZINE COUPLING**
  - **MATE/TRANSFER HYDRAZINE/DEMATE**
- **MARTIN MARIETTA SERVICING DEMO:**
  - **TO BE PERFORMED IN MMC LAB**
  - **FLY, DOCK, ENGAGE/DISENGAGE URIS, UNDOCK**
- **TRW SERVICING DEMO:**
  - **TO BE PERFORMED AT TRW**
  - **POSSIBLY A THERMAL/VAC FUNCTIONAL TEST**